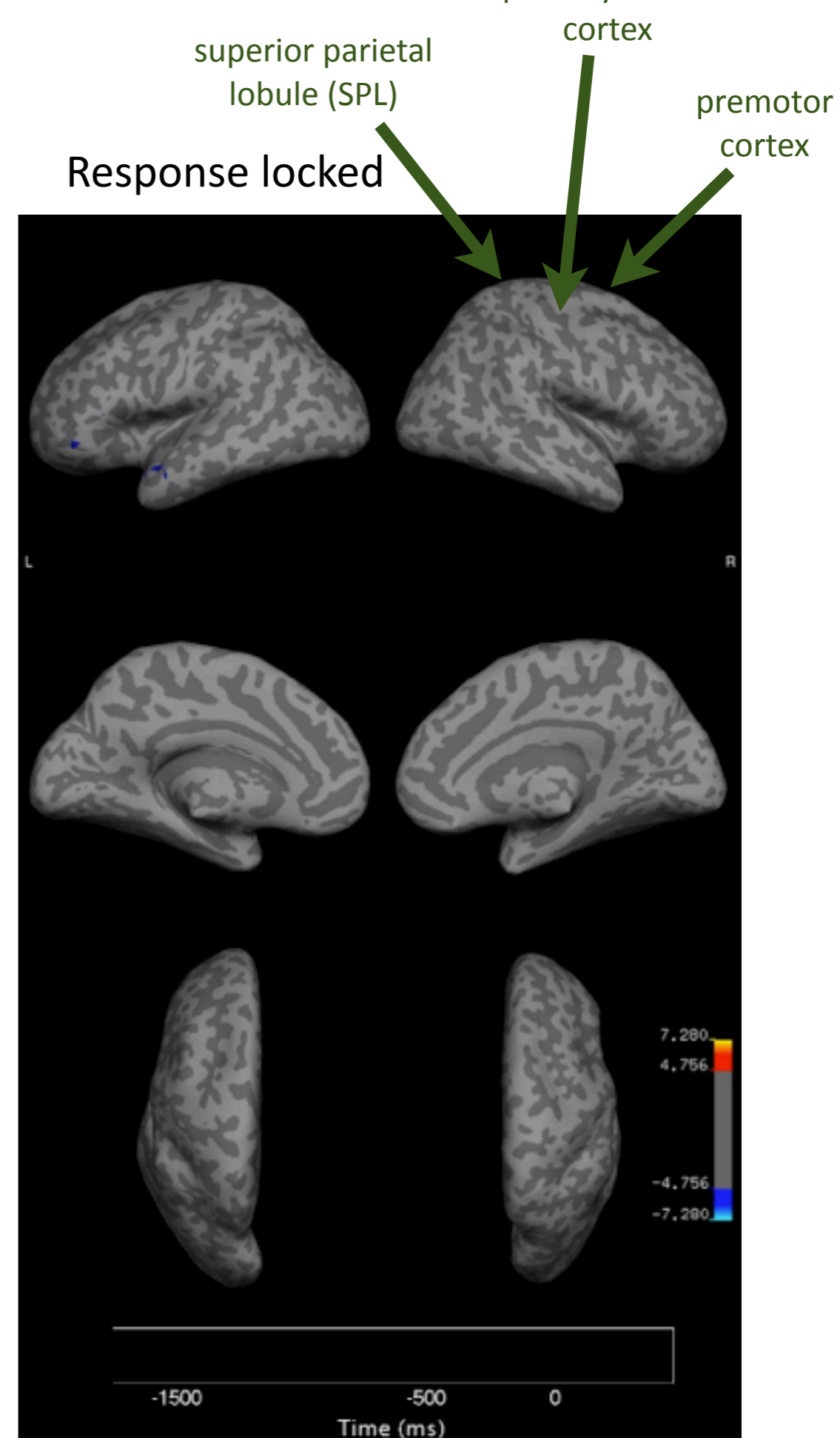
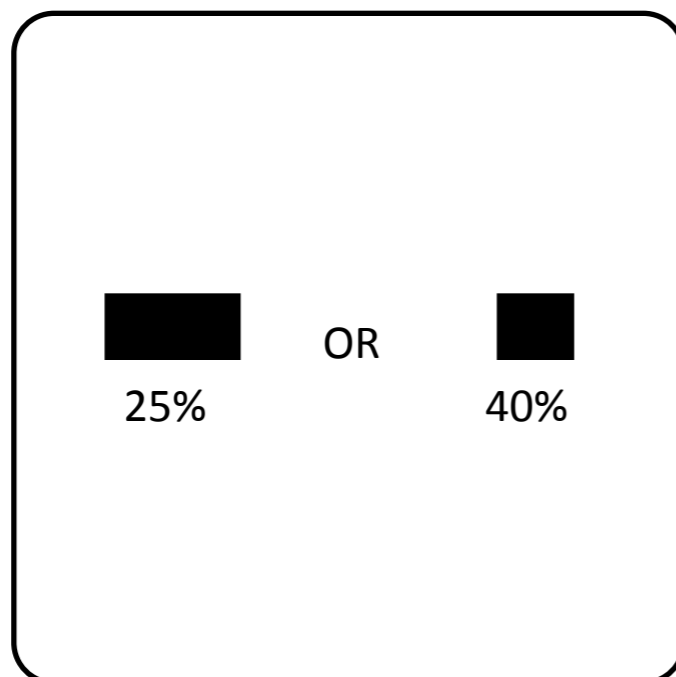


# Using OSL: Sensor Space Analyses

OHBA Analysis Workshop

*Mark Woolrich*

- Induced analysis of the decision making period:
  - **source reconstruction**
  - **epoching**: time-locked to when the response is given
  - compute the **average evoked power** (the induced response, ERD/ERS) from 1-12Hz
  - **group averaged** over 30 subjects



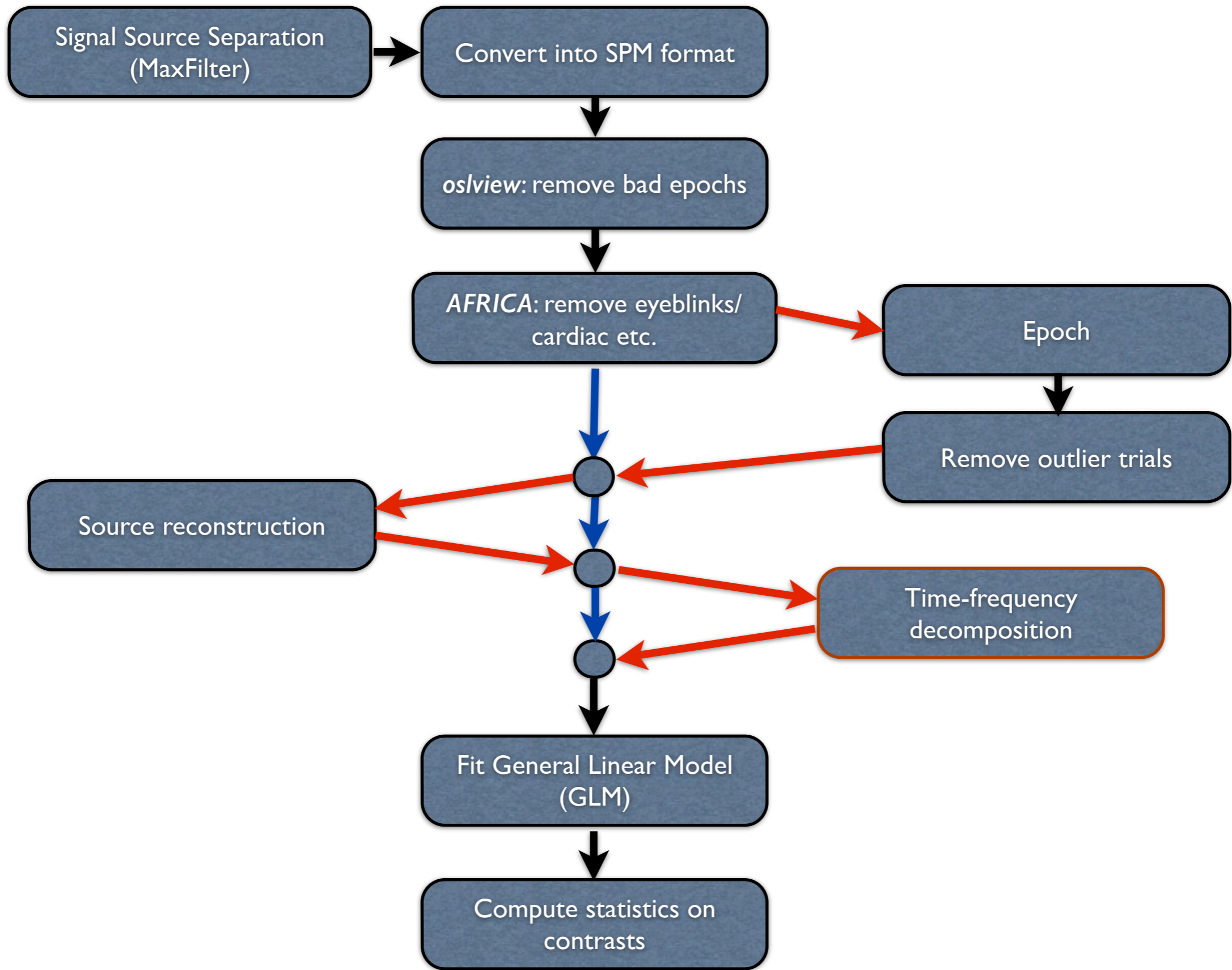
Hunt et al., Nature Neuroscience, 2012.

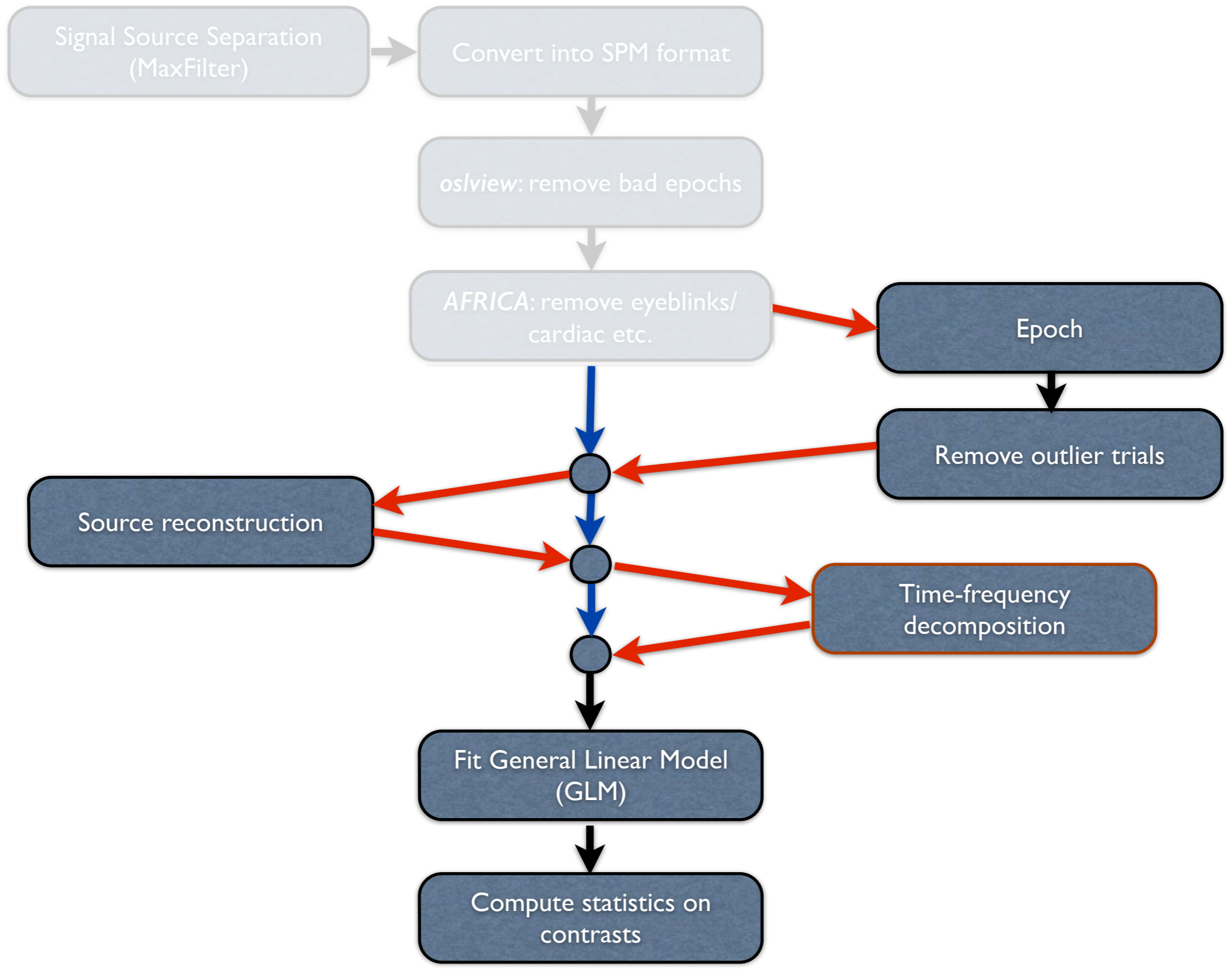
# Talk Outline

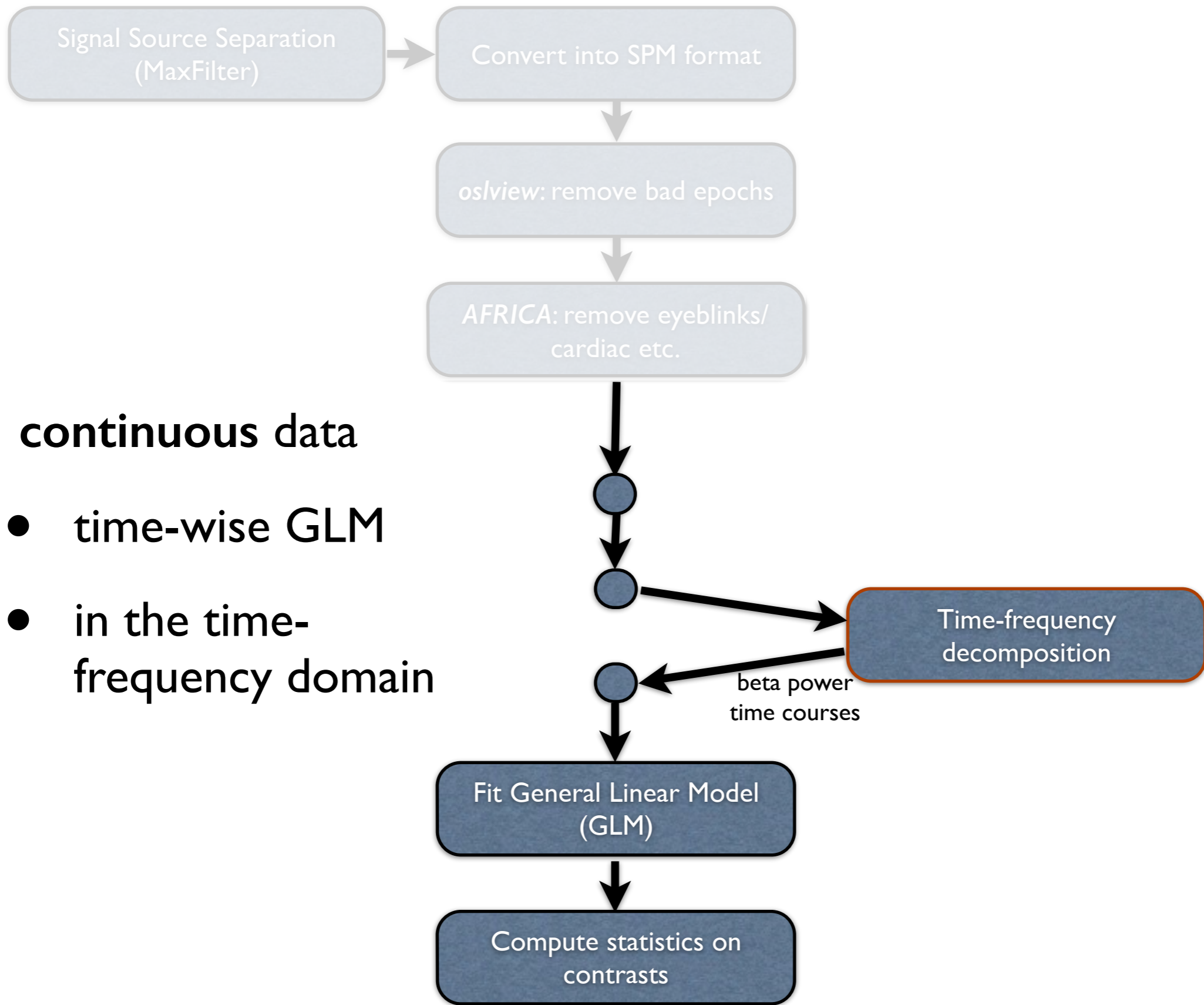
- Analysing continuous data in sensor space
  - time-wise GLM
- Analysing epoched data in sensor space
  - trial-wise GLM
- OSL (OHBA's Software Library):
  - OAT (OSL's Analysis Tool)

# Continuous Data Example

- Finger tapping versus rest
- 20sec blocks of alternating:
  - ➡ rest
  - ➡ finger tapping
- We want to compare changes in beta power (13-30 Hz)



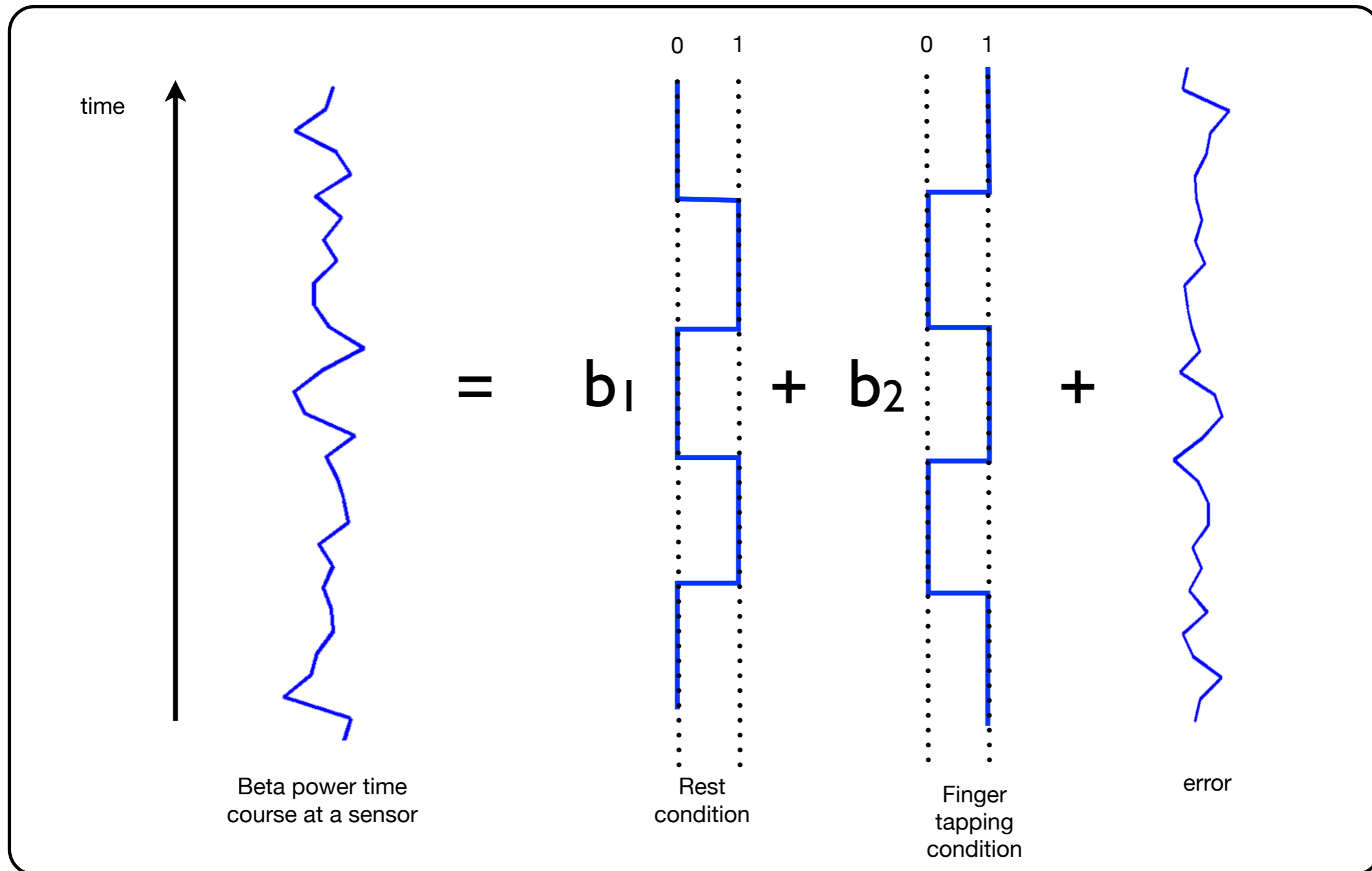




- **continuous data**
- **time-wise GLM**
- **in the time-frequency domain**

# Continuous Data Time-wise

## Example

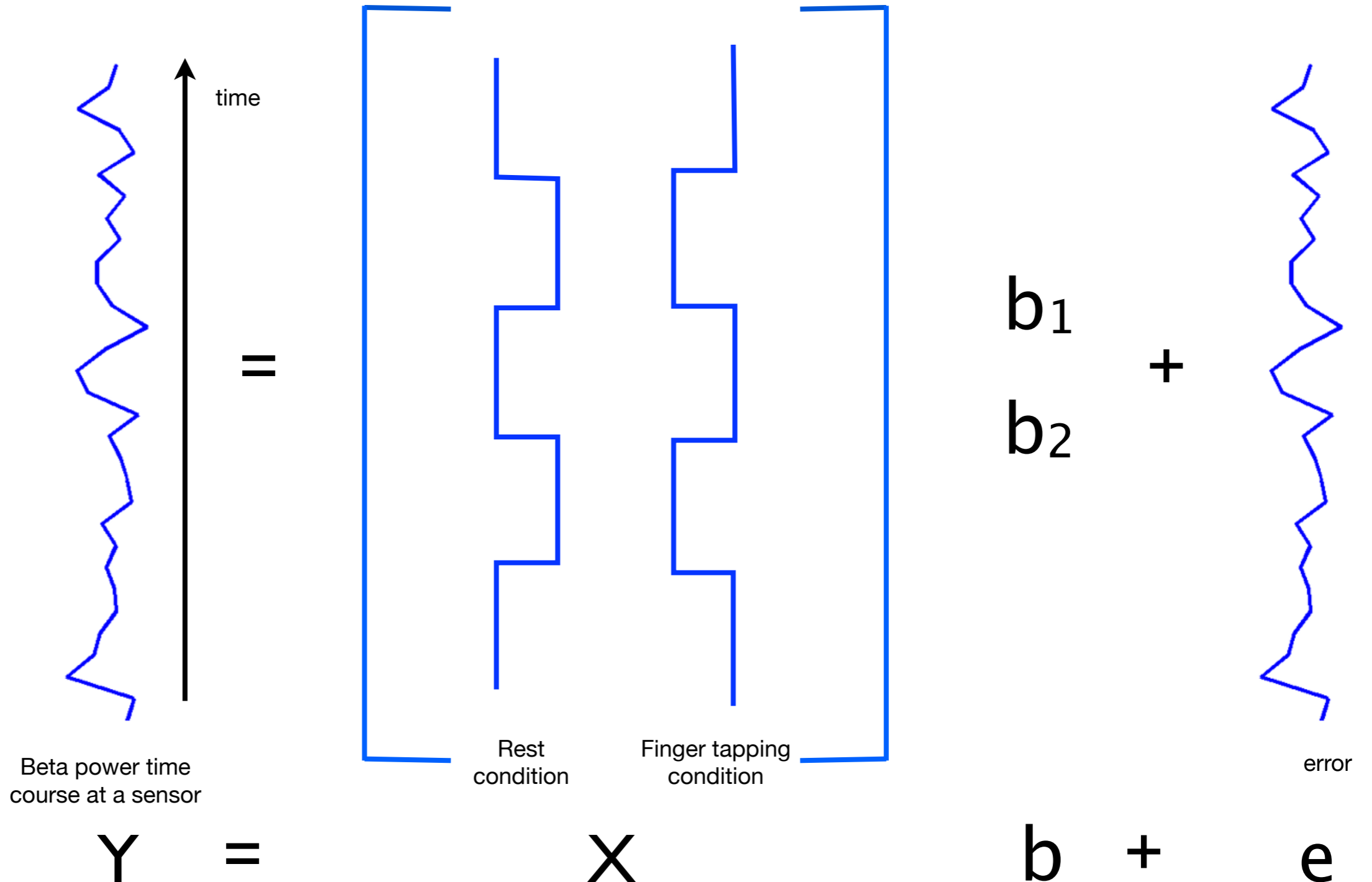




# Time-wise GLM Example

More formally we fit (for each sensor) a General Linear Model (GLM):

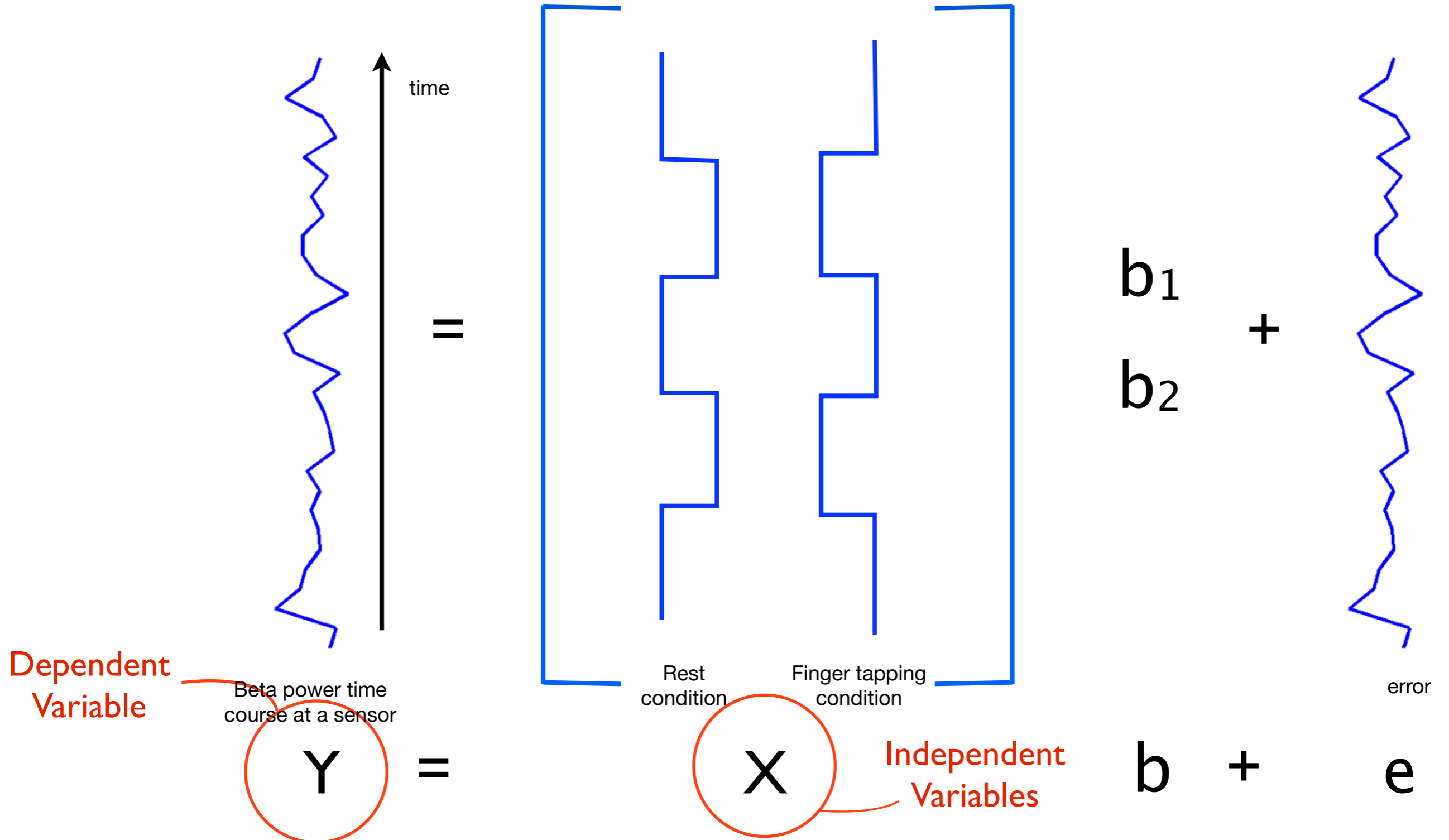
## Design Matrix



# Time-wise GLM Example

More formally we fit (for each sensor) a General Linear Model (GLM):

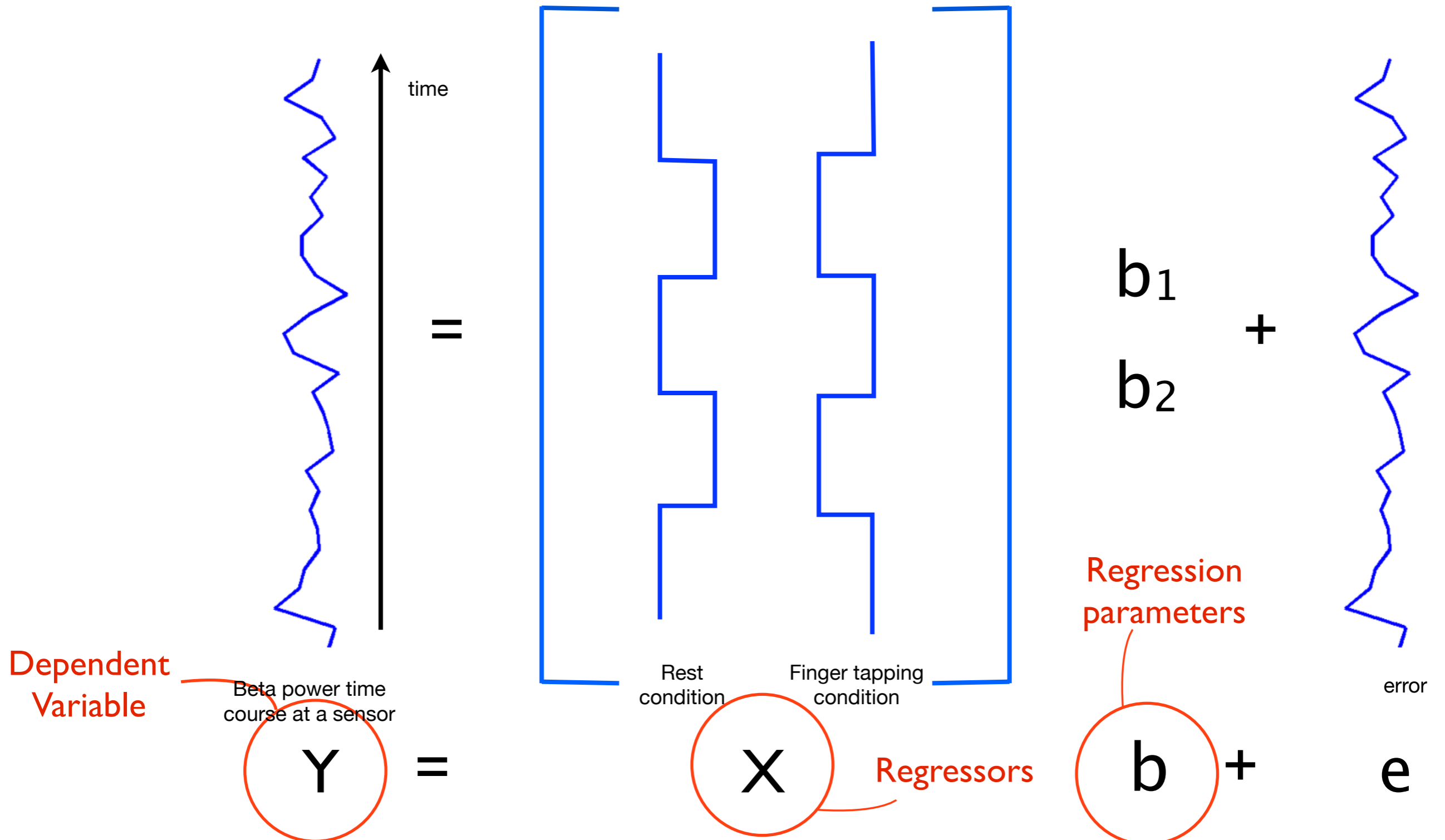
## Design Matrix



# Time-wise GLM Example

More formally we fit (for each sensor) a General Linear Model (GLM):

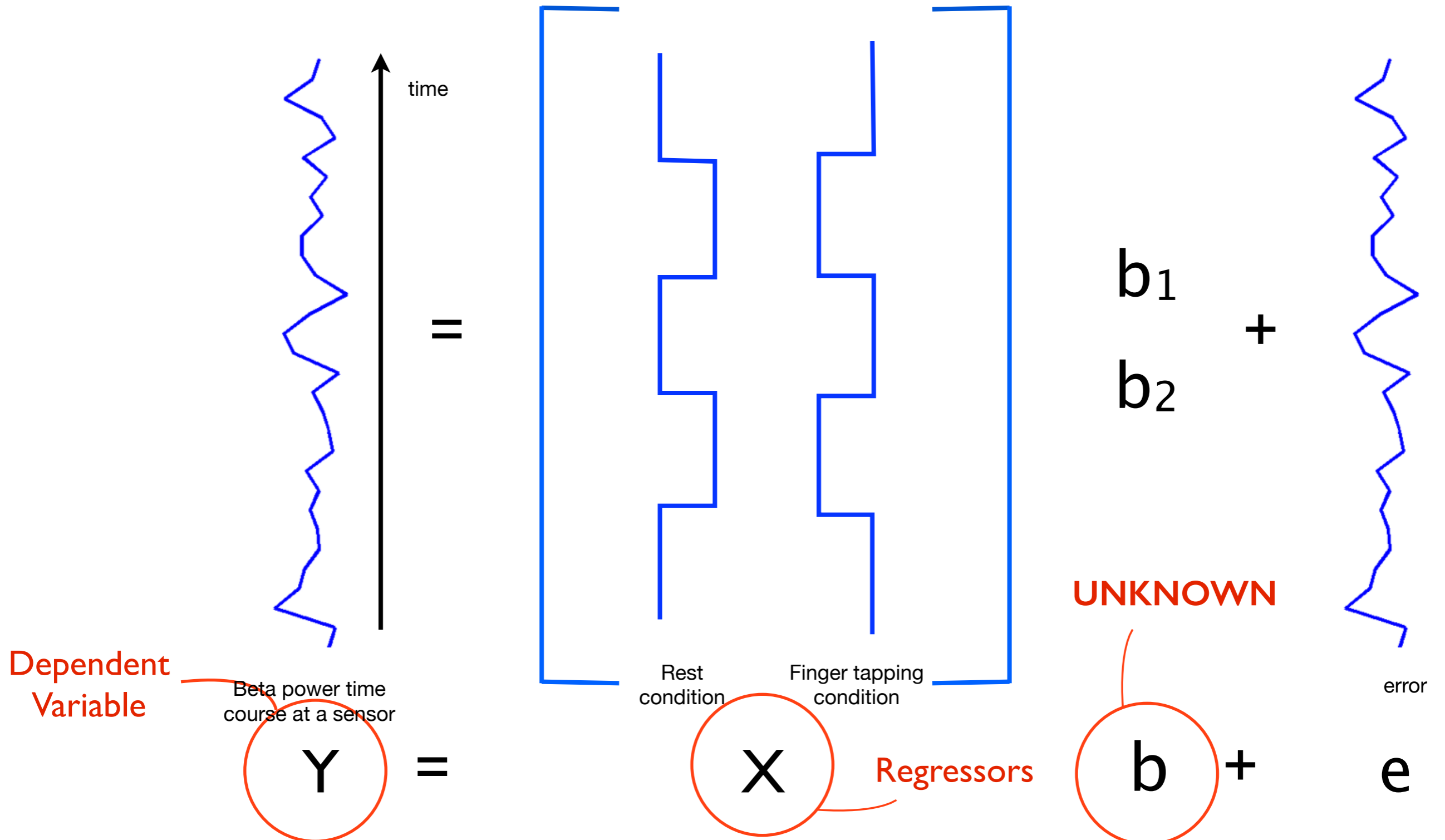
## Design Matrix



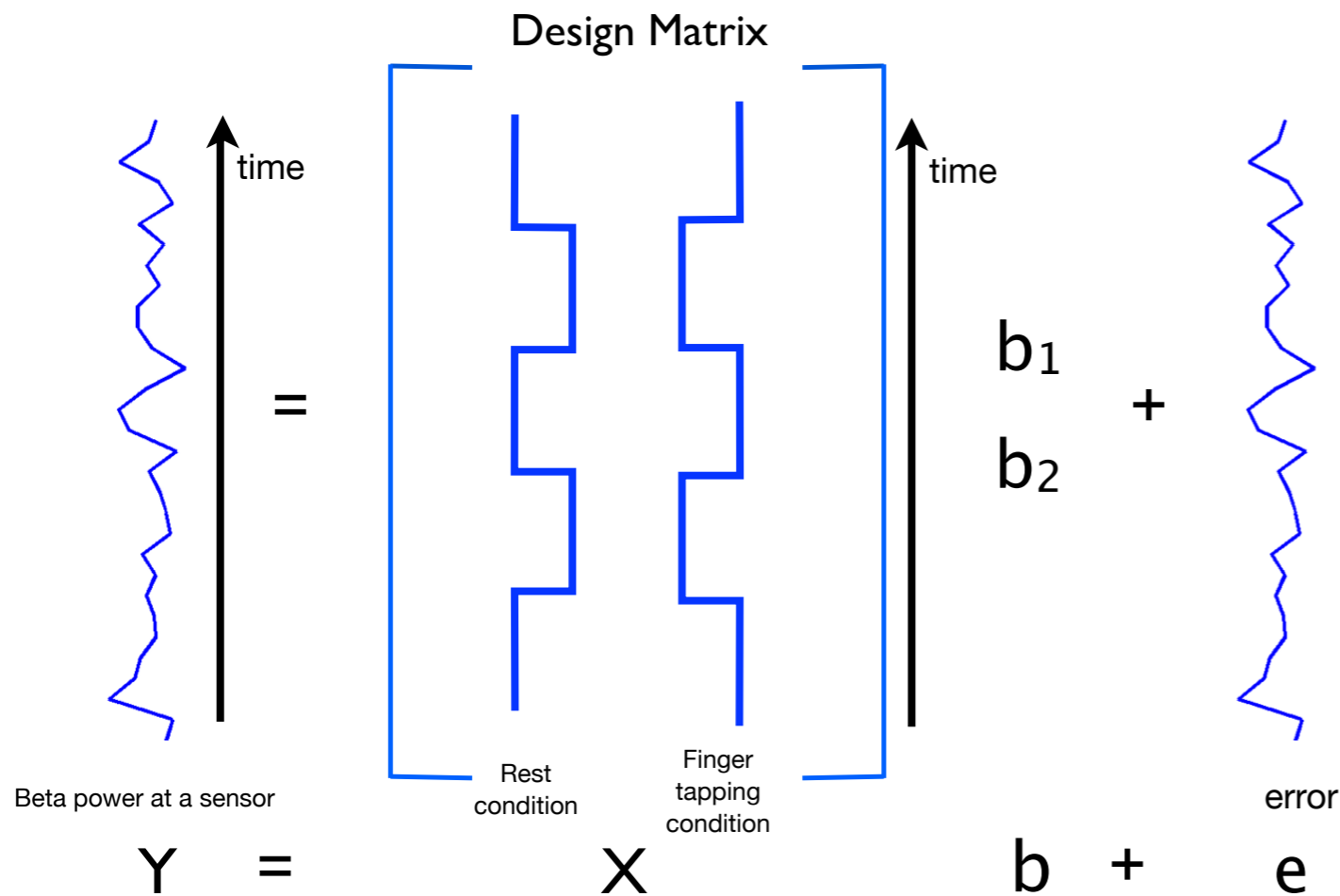
# Time-wise GLM Example

More formally we fit (for each sensor) a General Linear Model (GLM):

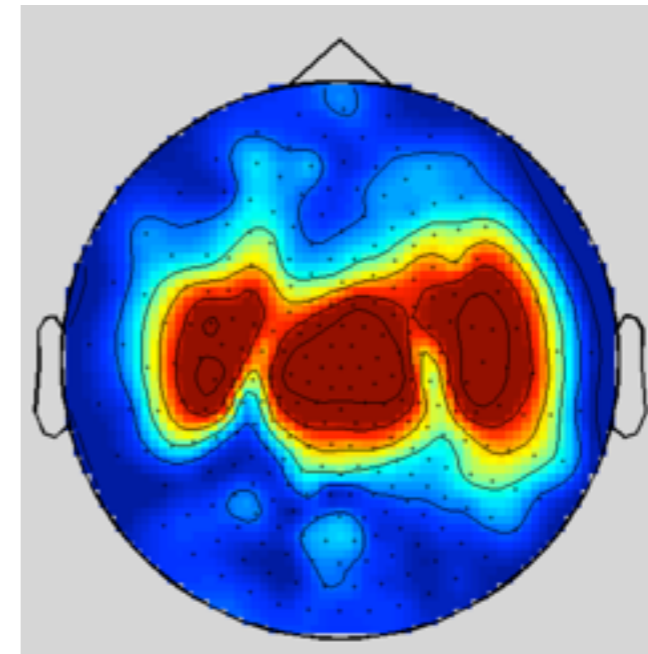
## Design Matrix



# GLM can be fitted at each sensor



Sensor (topographic) map of mean beta power decrease between finger tapping and rest, i.e.  $B_1 - B_2$



Repeat for all sensors

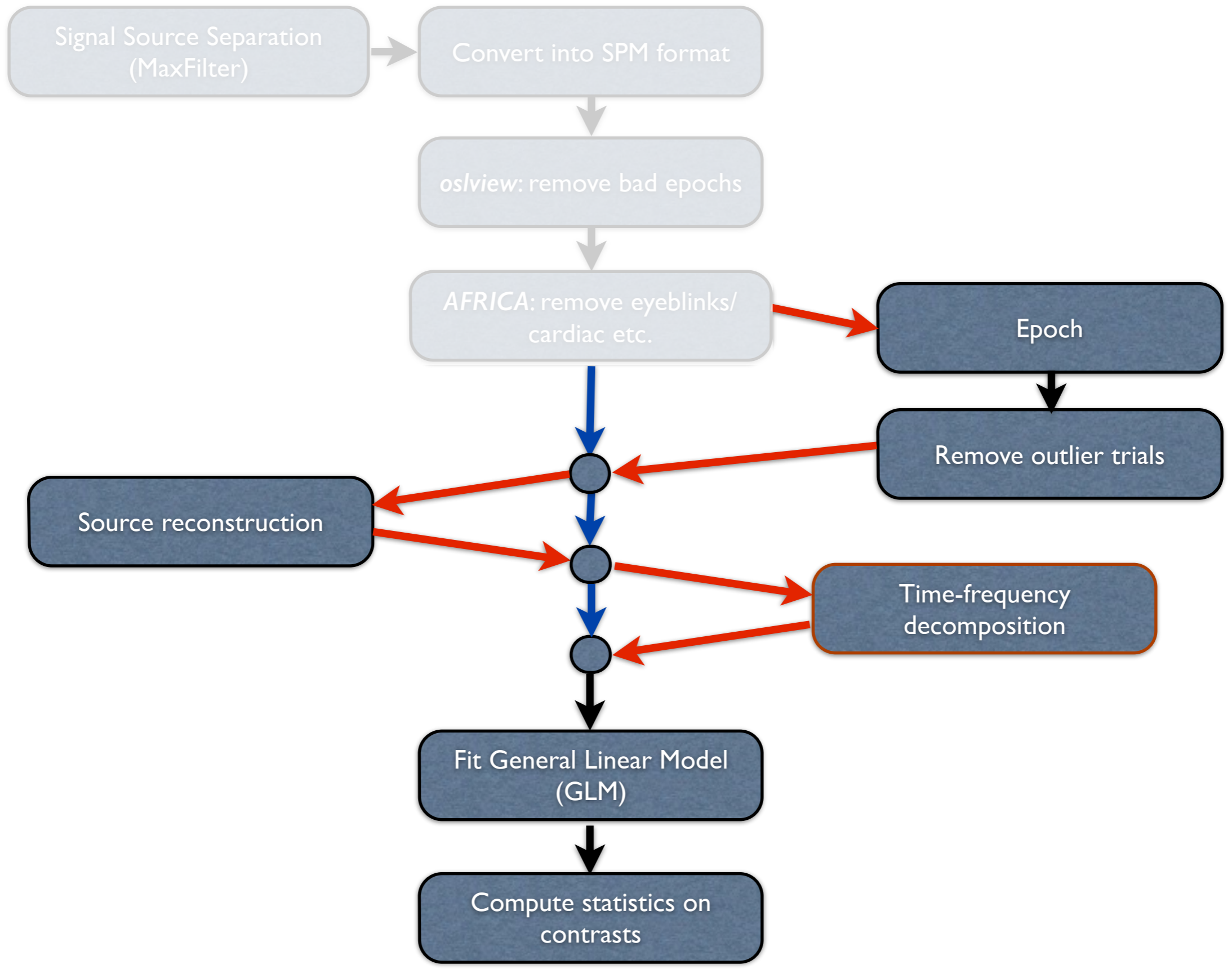
$$Y = Xb + e$$

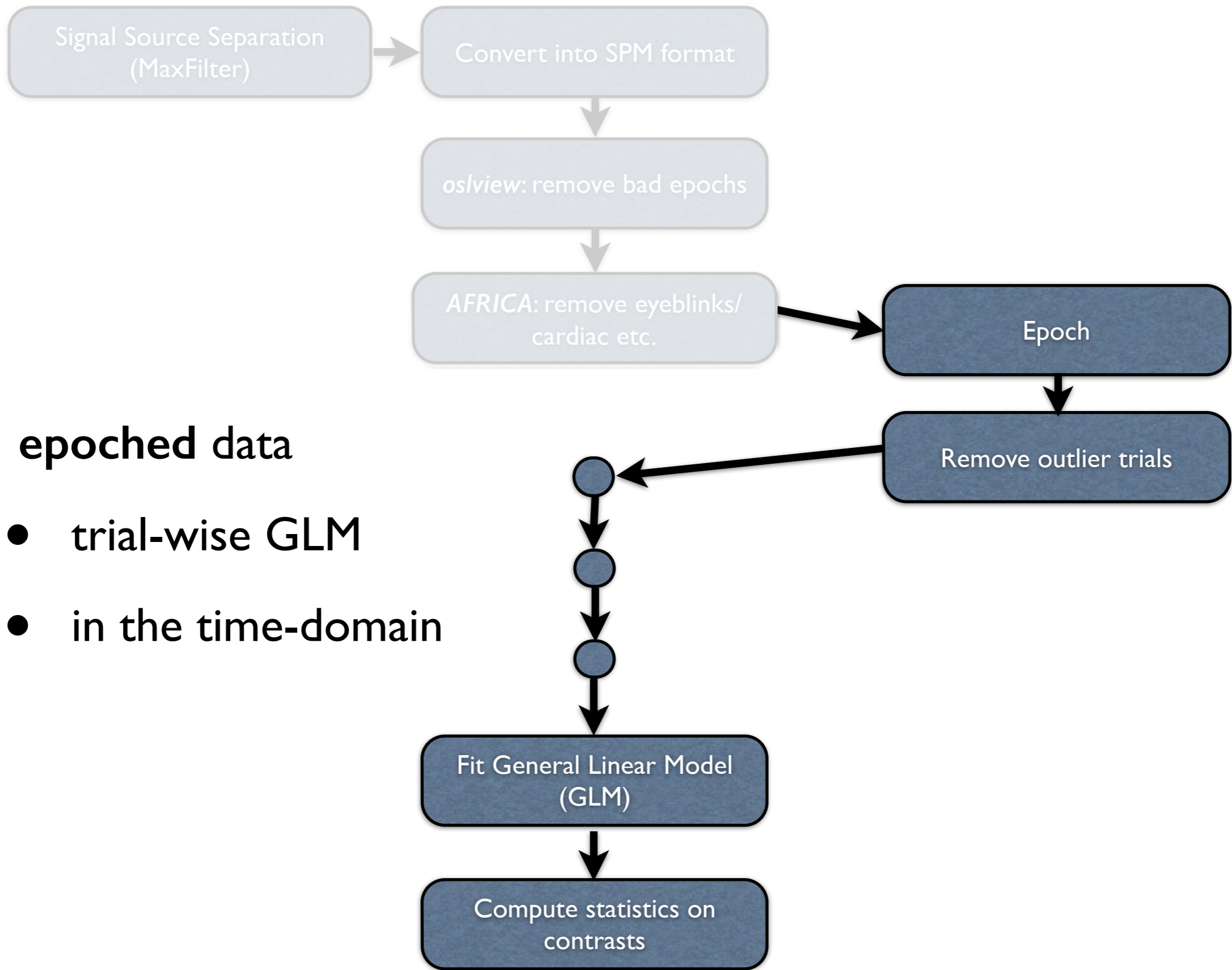


Ordinary Least Squares (OLS) estimate  $B = [B_1, B_2]$ , which are the Parameter Estimates (PEs) of  $b$

# Epoched Data Example

- **Faces versus motorbikes**
  - ➔ 240 trials (epochs) of presenting pictures of faces
  - ➔ 120 trials (epochs) of presenting pictures of motorbikes
- **We want to compare the responses time-locked to stimulus presentation (i.e. the Event-Related Fields (ERFs))**



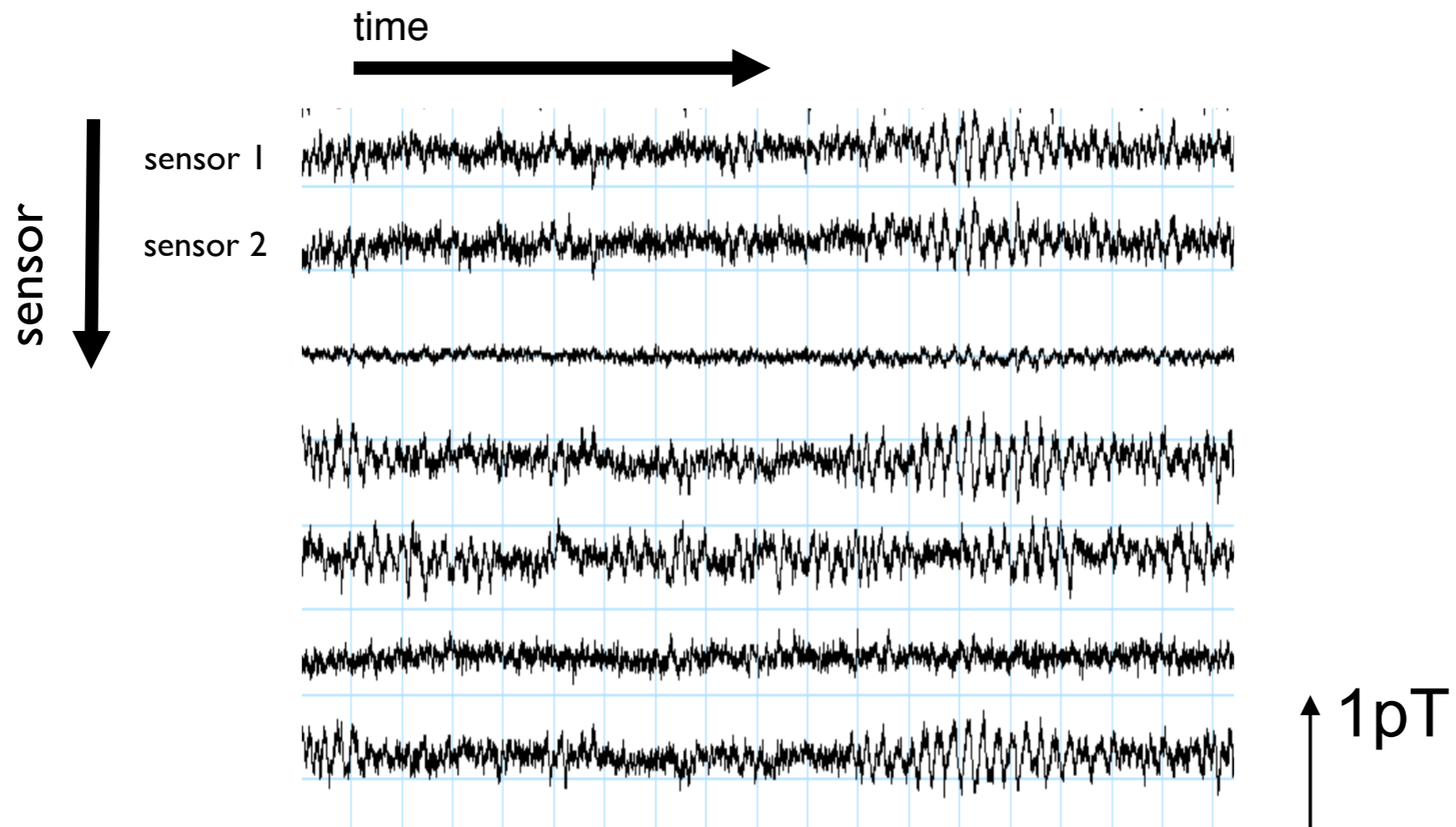


- **epoched data**
  - trial-wise GLM
  - in the time-domain



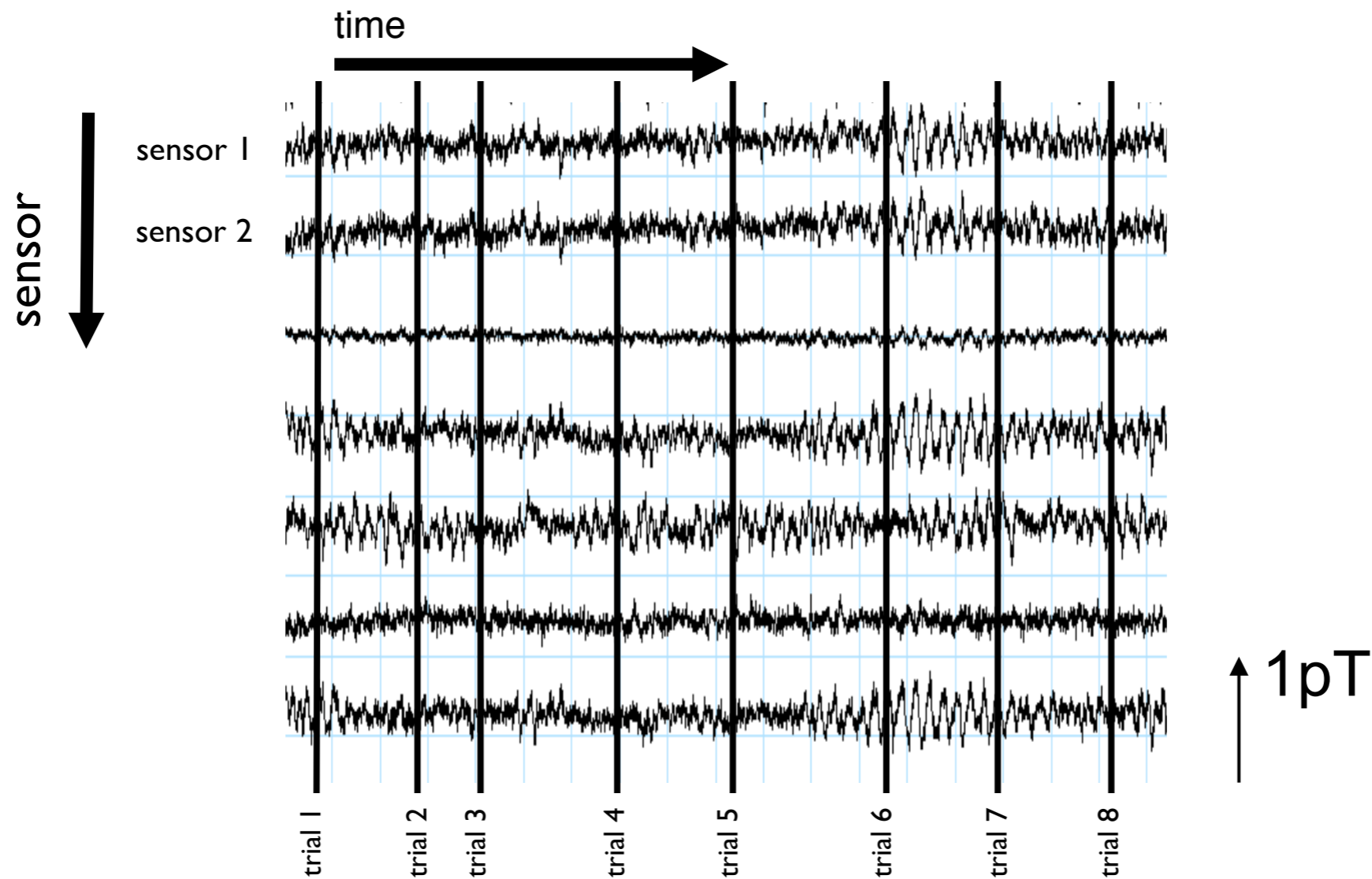
# Epoching and ERFs

Epoching takes continuous 2D data:  
*sensors x timepoints*



# Epoching and ERFs

Epoching takes continuous 2D data:  
*sensors x timepoints*



# Epoching and ERFs

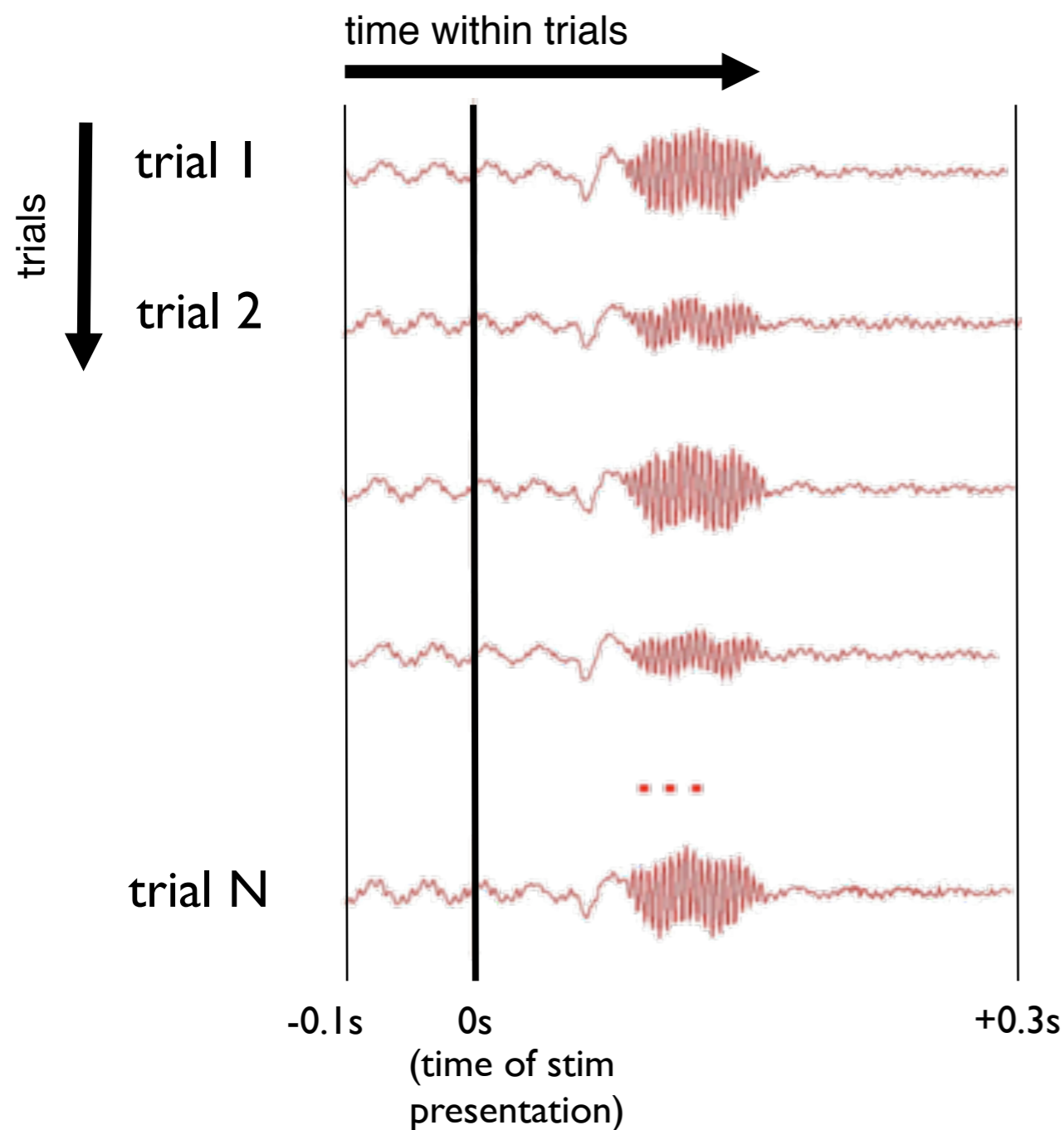
Epoching takes continuous 2D data:

*sensors x timepoints*

and produces epoched 3D data:

*sensors x trials x timepoints-within-trial*

E.g. at one sensor:



# Epoching and ERFs

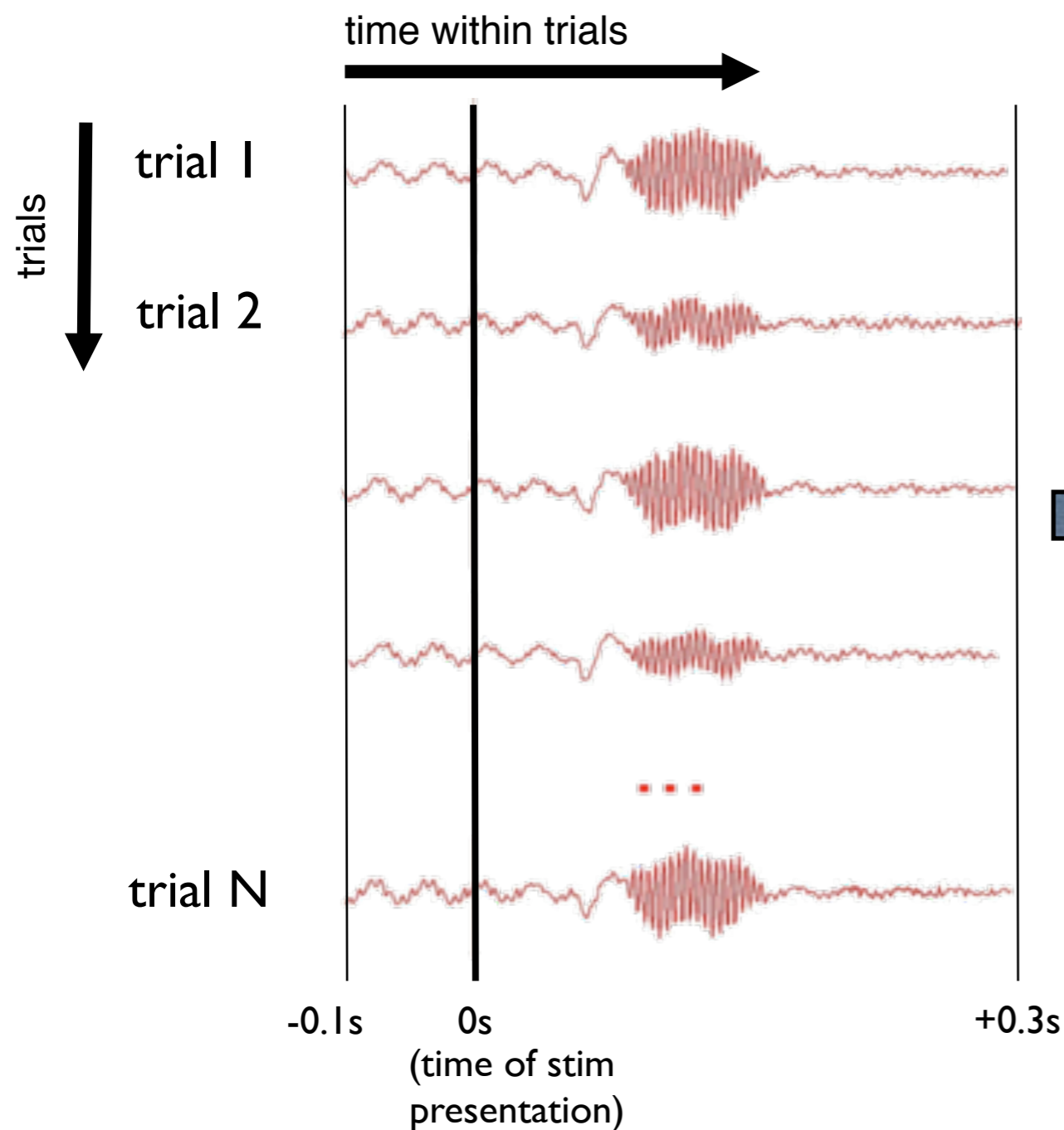
Epoching takes continuous 2D data:

*sensors x timepoints*

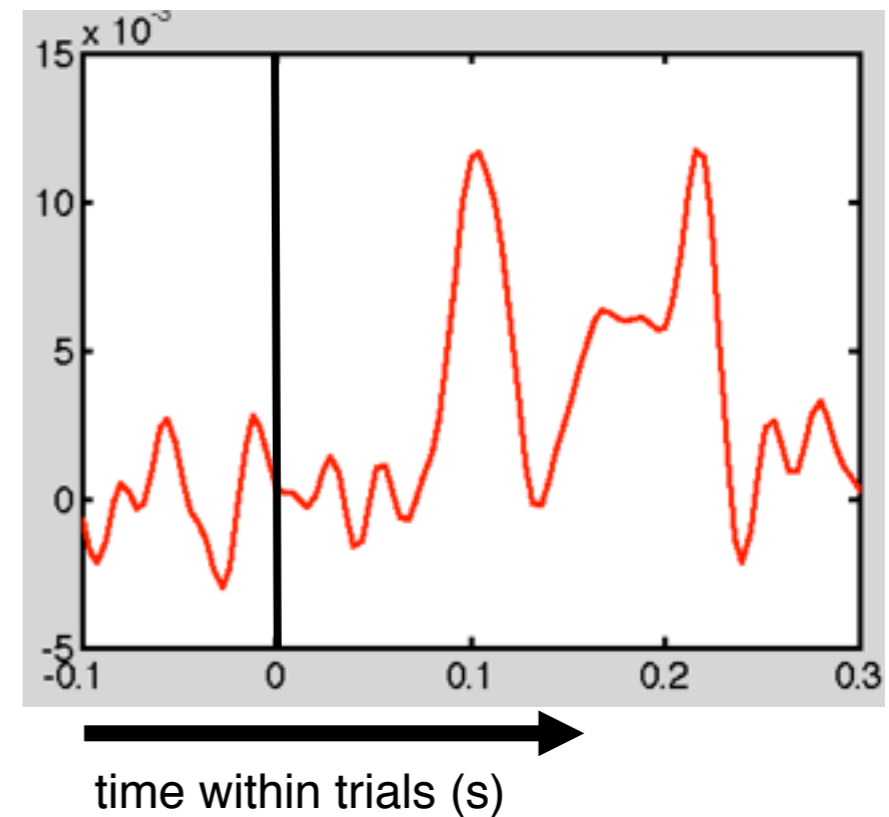
and produces epoched 3D data:

*sensors x trials x timepoints-within-trial*

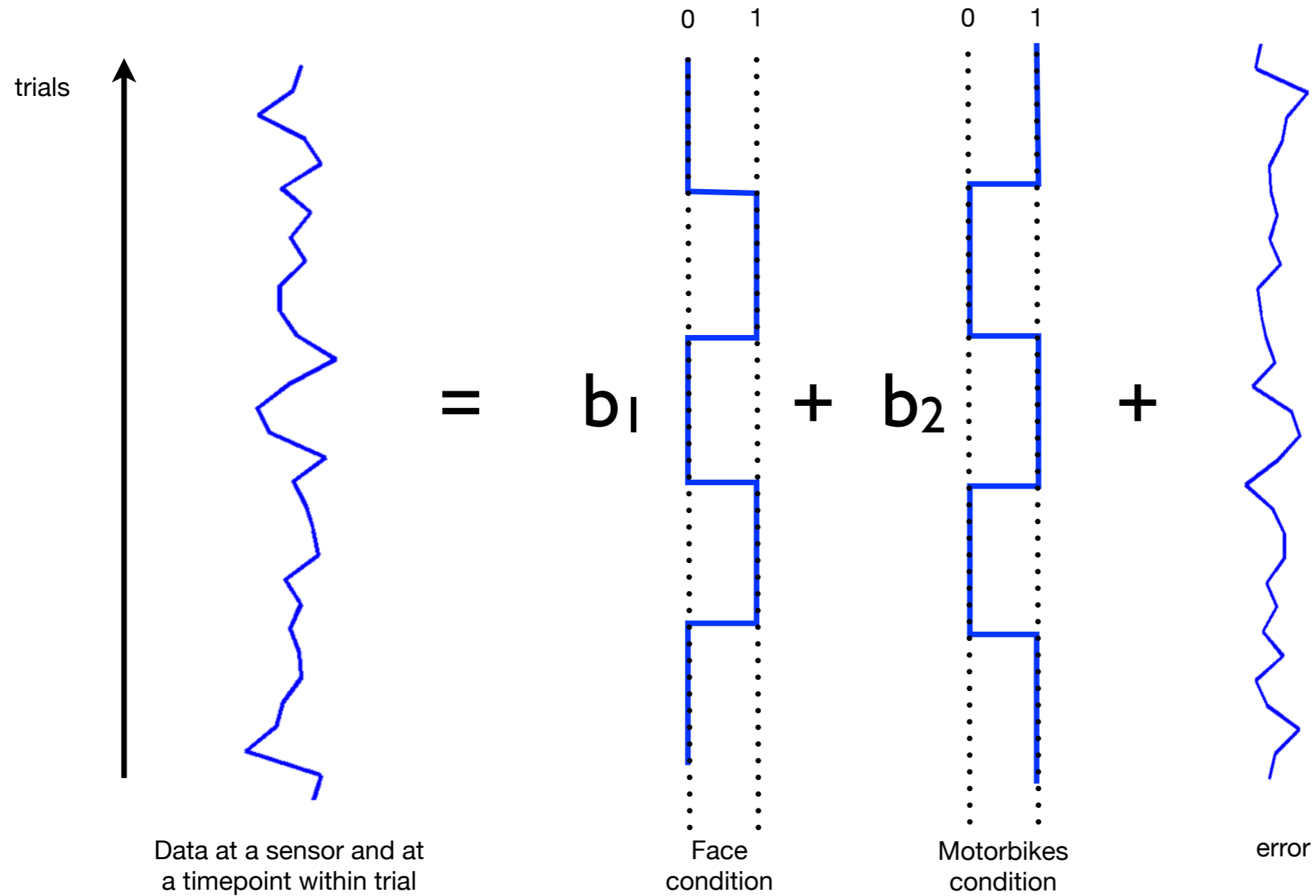
E.g. at one sensor:



Average over all "face" epochs/  
trials to get a face Event  
Related Field (ERF):

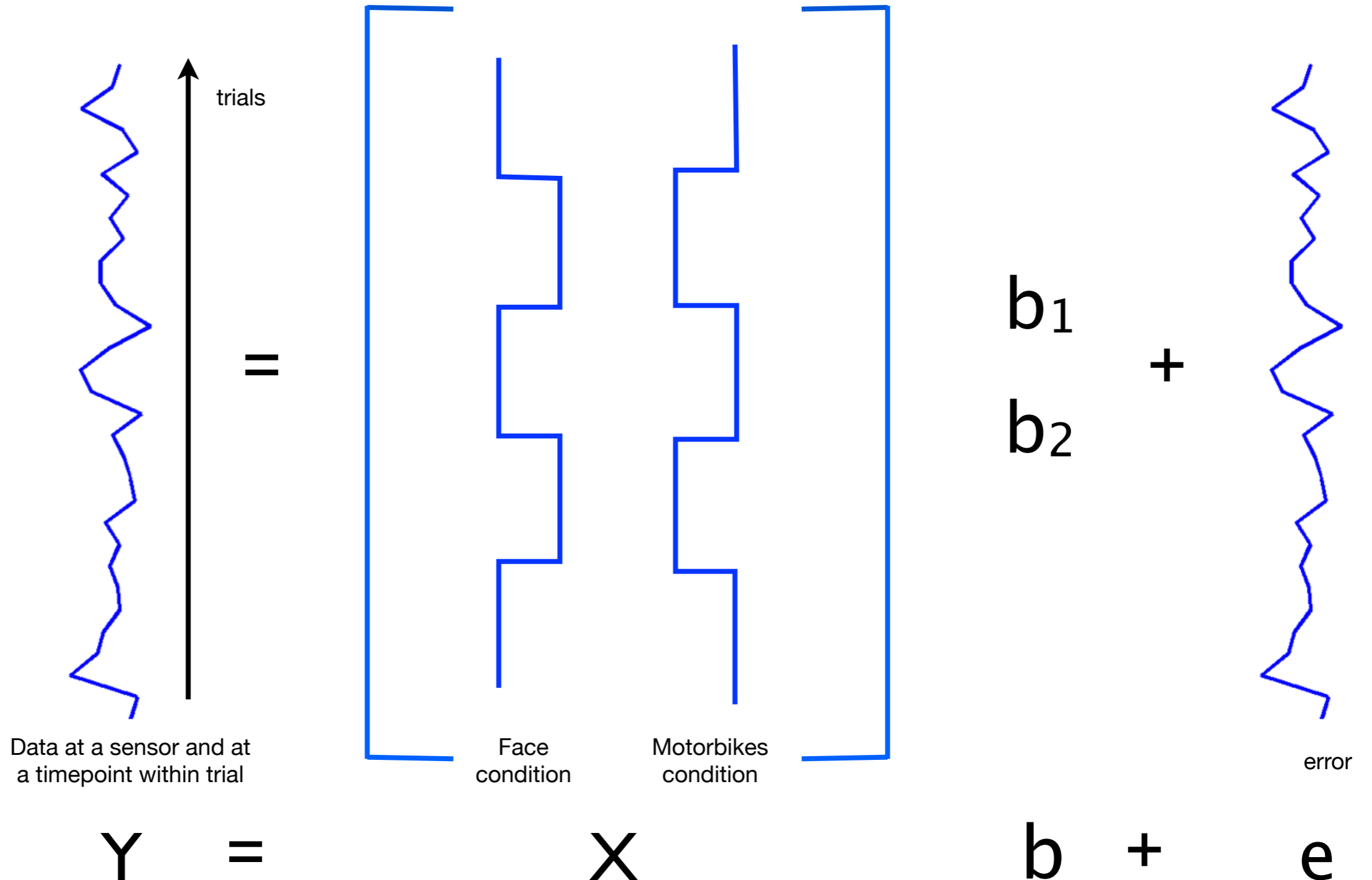


# Trial-wise GLM

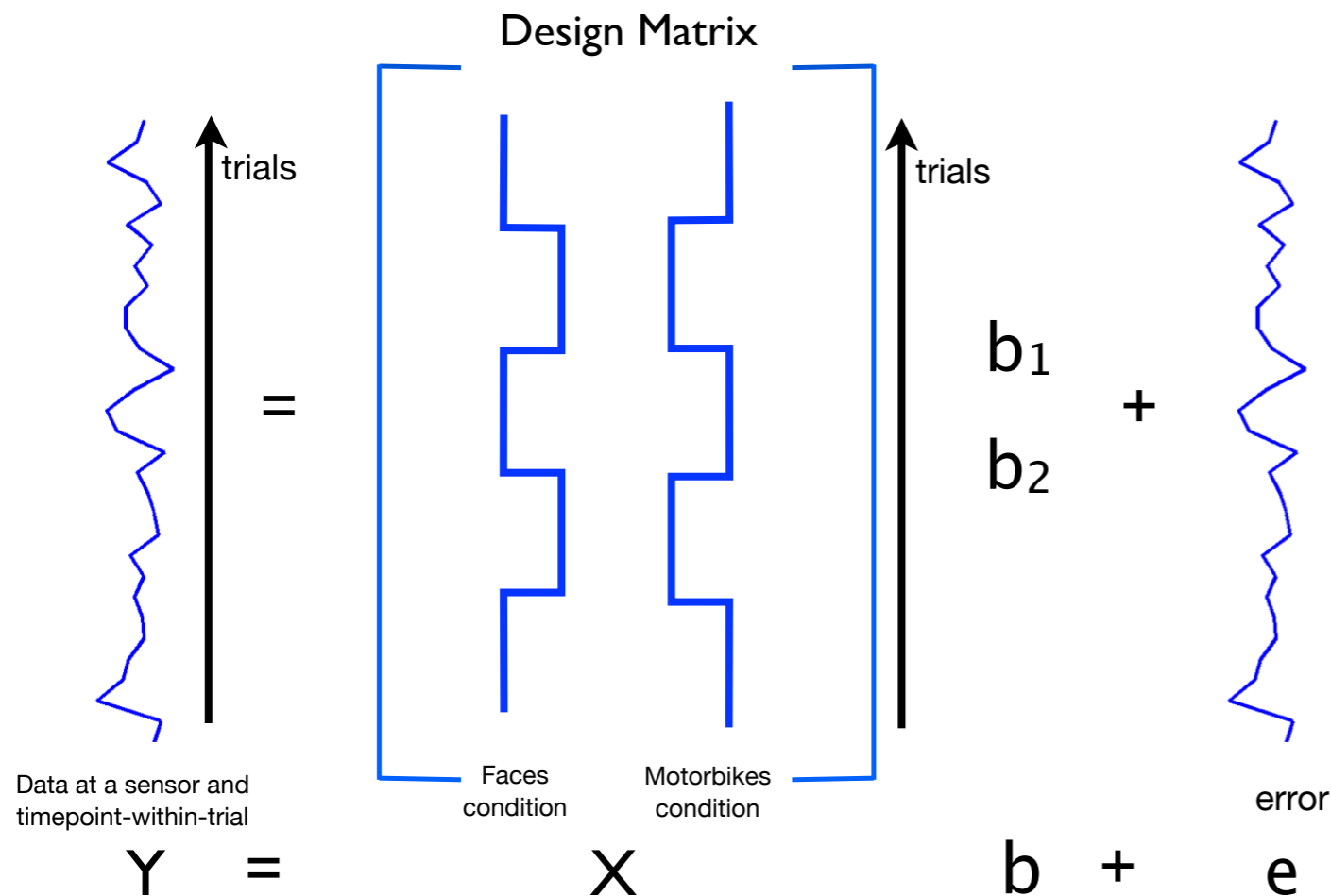


# Trial-wise GLM

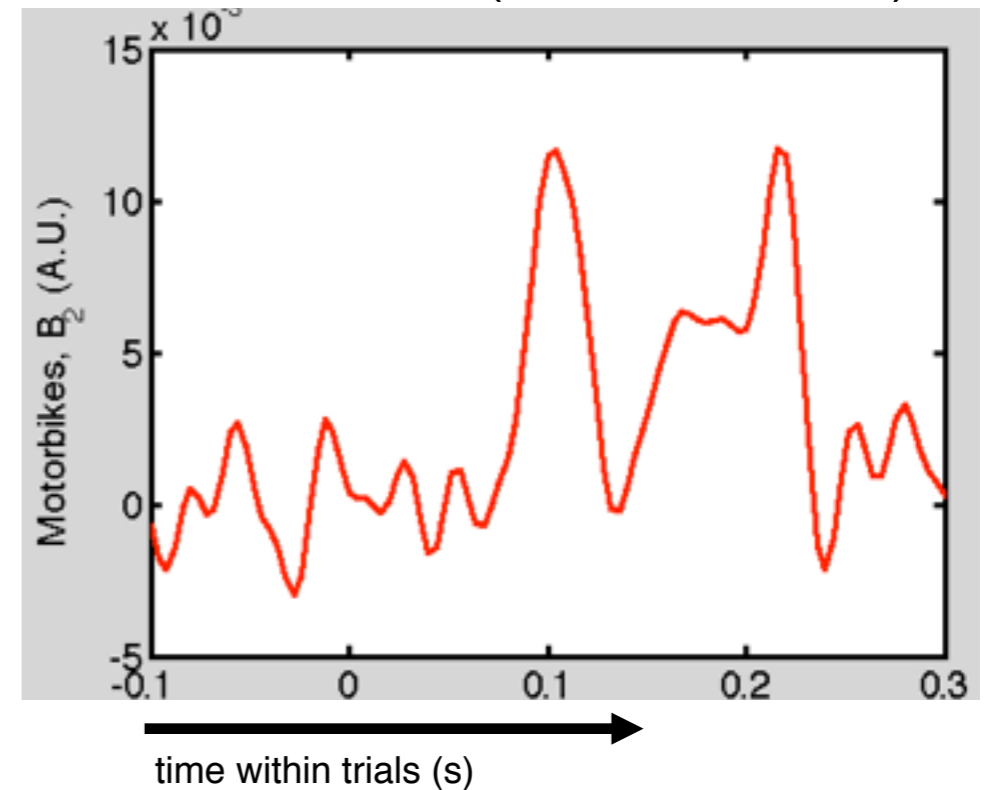
## Design Matrix



# GLM can be fit to each time-point within trial

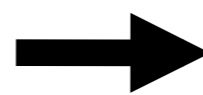


Motorbikes ( $B_2$ ) at a sensor near the visual cortex (motorbike ERF)



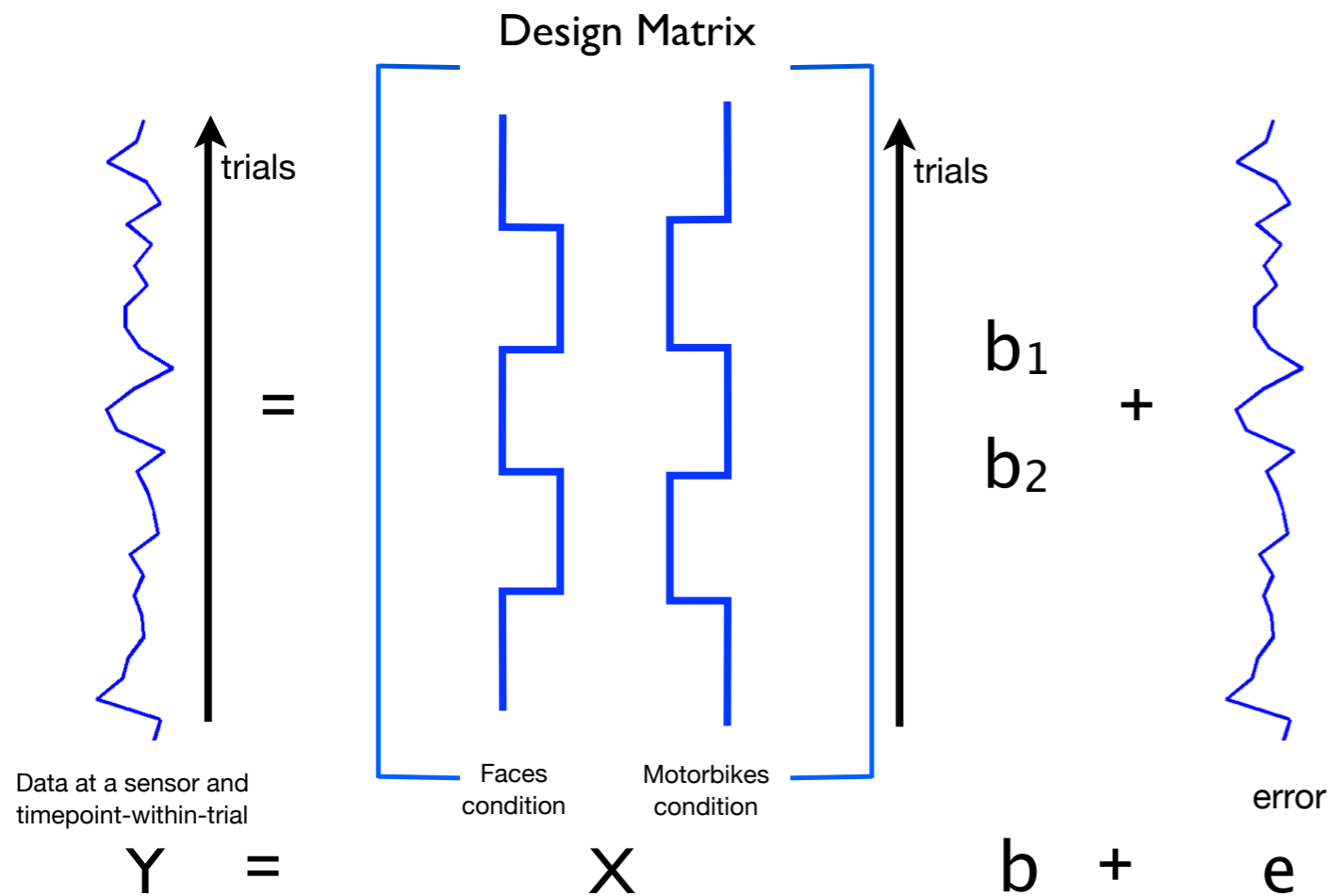
Repeat for all timepoints within-trial at a sensor

$$Y = Xb + e$$



Estimate  $B$ , which are the Parameter Estimates (PEs) of  $b$

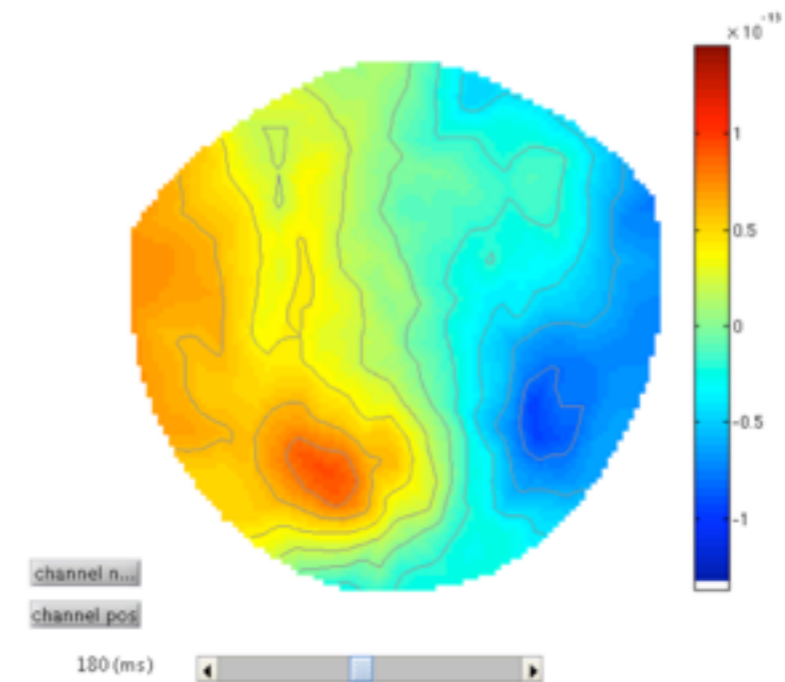
# The GLM can be fit to each sensor



$$Y = Xb + e$$



Motorbikes ( $B_2$ ) at 100ms post-stimulus



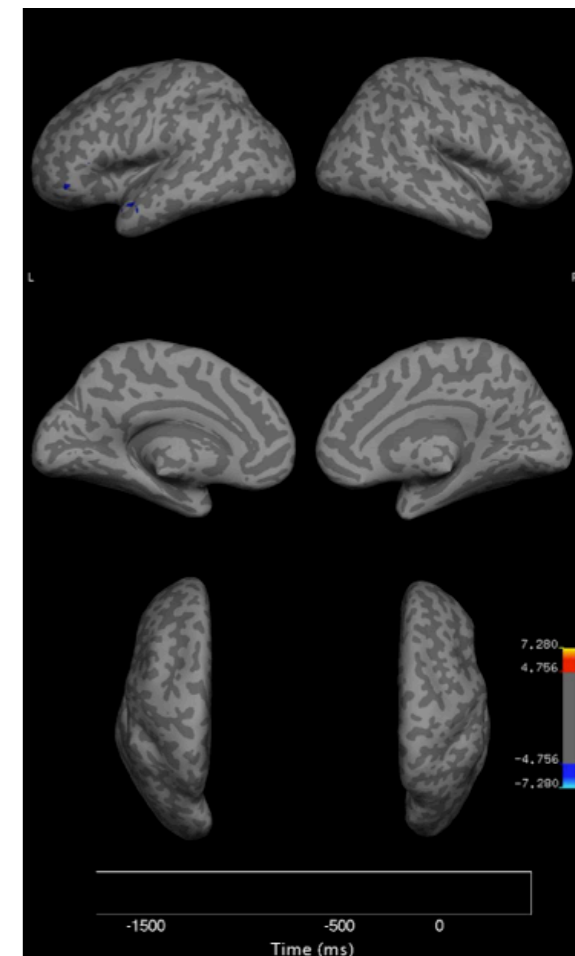
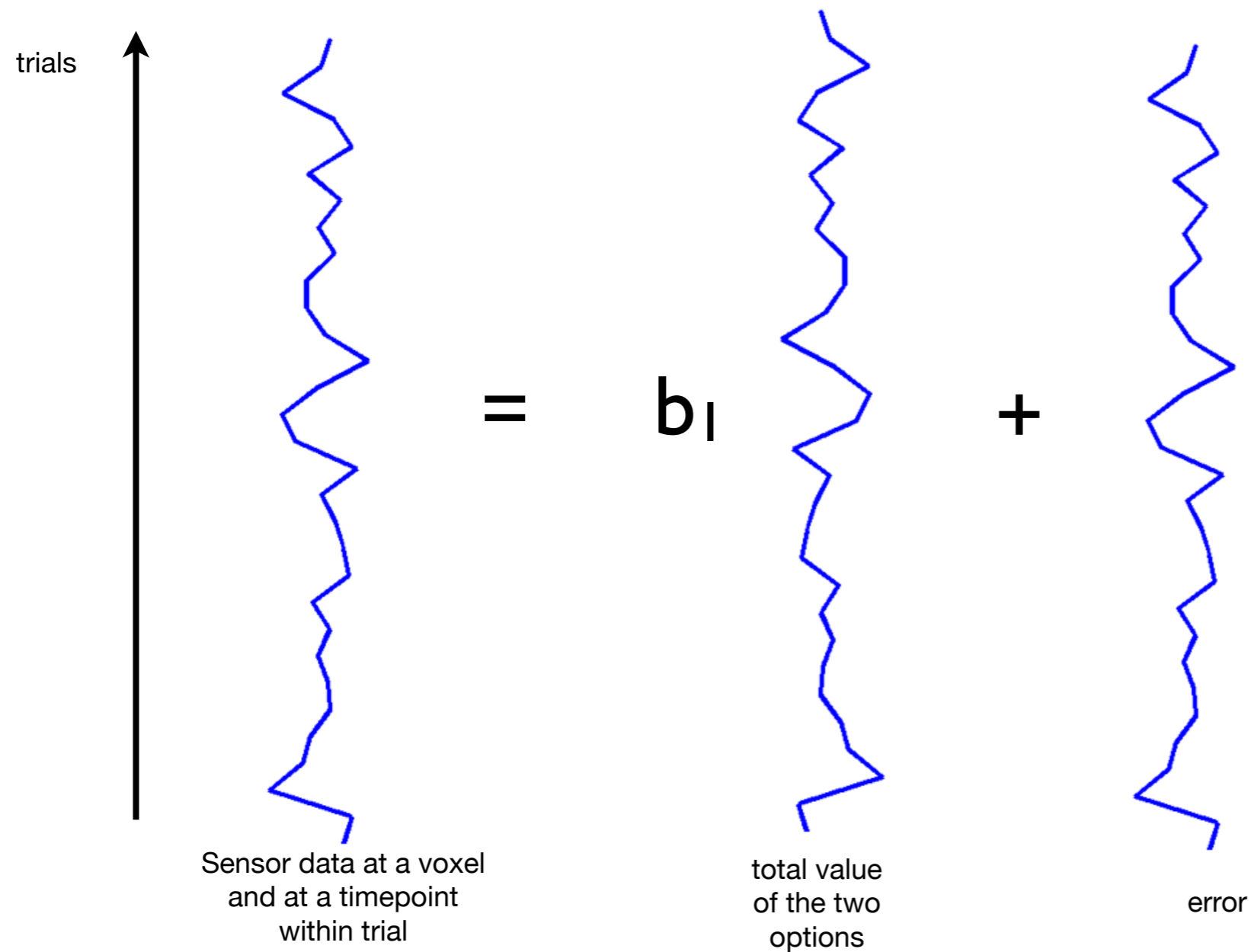
Repeat for all sensors at a time-within-trial

Estimate  $B$ , which are the Parameter Estimates (PEs) of  $b$



# GLM

Note that the GLM is a general framework, e.g. in which we can also fit continuous variables:

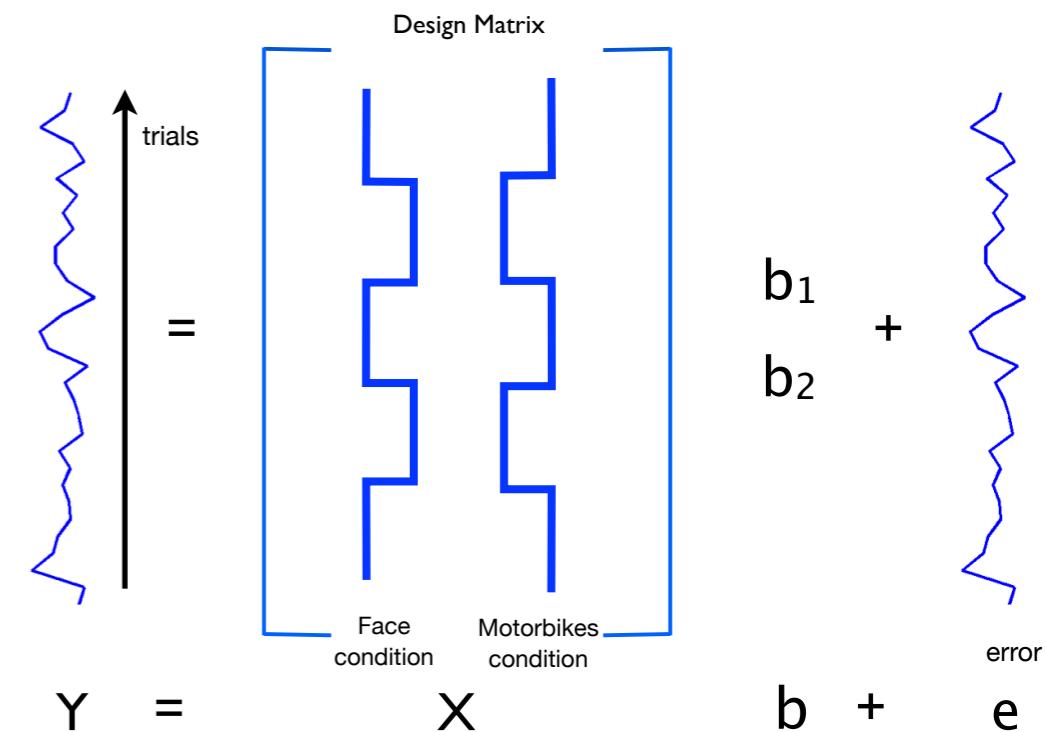


# Contrasts

A **CO**ntrast of Parameter Estimates (**COPE**) is a linear combination of the regression parameter estimates, e.g.

Contrast  $[1 \ 0]$  gives a COPE  $= 1 \times B_1 + 0 \times B_2$   
 $= B_1$

Contrast  $[1 \ -1]$  gives a COPE  $= 1 \times B_1 - 1 \times B_2$   
 $= B_1 - B_2$

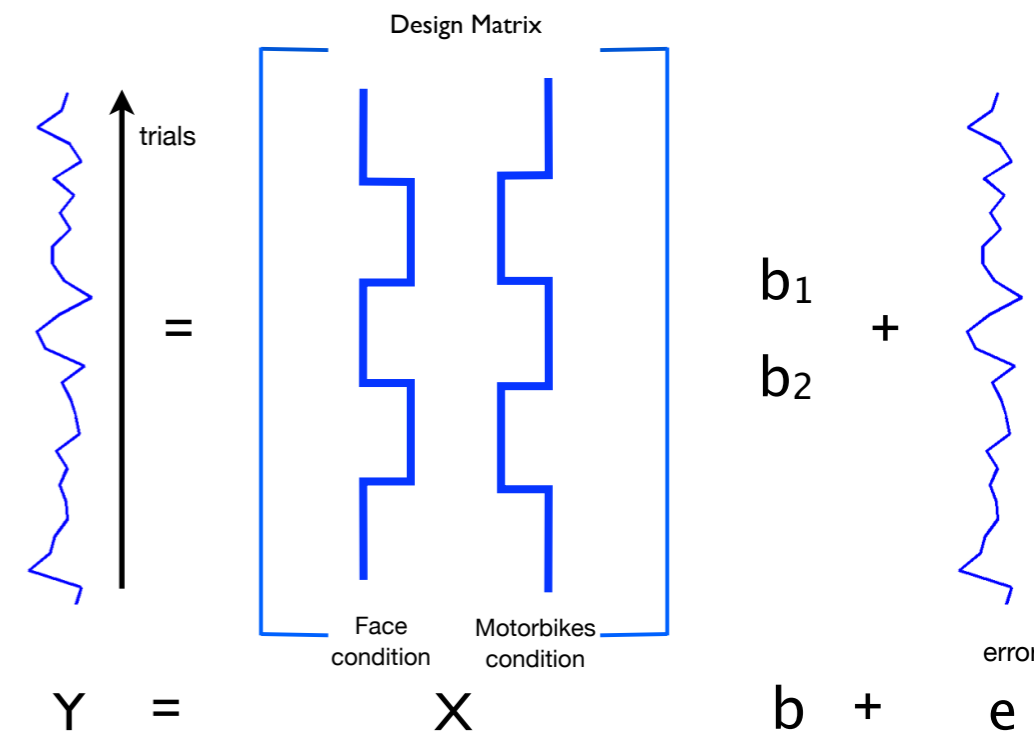


# Contrasts

A COntrast of Parameter Estimates (COPE) is a linear combination of the regression parameter estimates, e.g.

Contrast [1 0] gives a COPE =  $1 \times B_1 + 0 \times B_2$   
 $= B_1$

Contrast [1 -1] gives a COPE =  $1 \times B_1 - 1 \times B_2$   
 $= B_1 - B_2$



Use a t-test to test the null hypothesis that COPE=0:

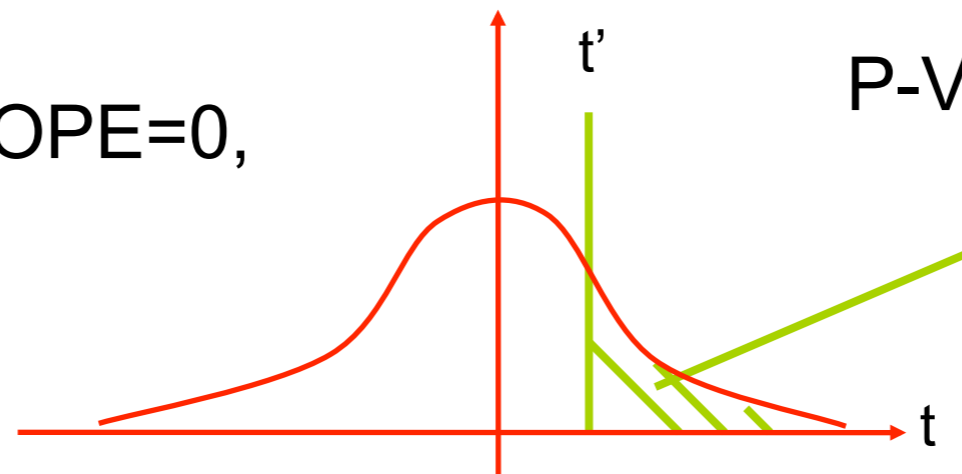
t-statistic:

$$t = \frac{COPE}{std(COPE)}$$

# Null Hypothesis Test

t-statistic: 
$$t = \frac{COPE}{std(COPE)}$$

Under null hypothesis,  $COPE=0$ ,  
 $t'$  is from a t-distribution



P-Value =  $\text{prob}(t > t' | COPE = 0)$   
(one-tailed test)

Small P-Value  $\Rightarrow$  null hypothesis unlikely

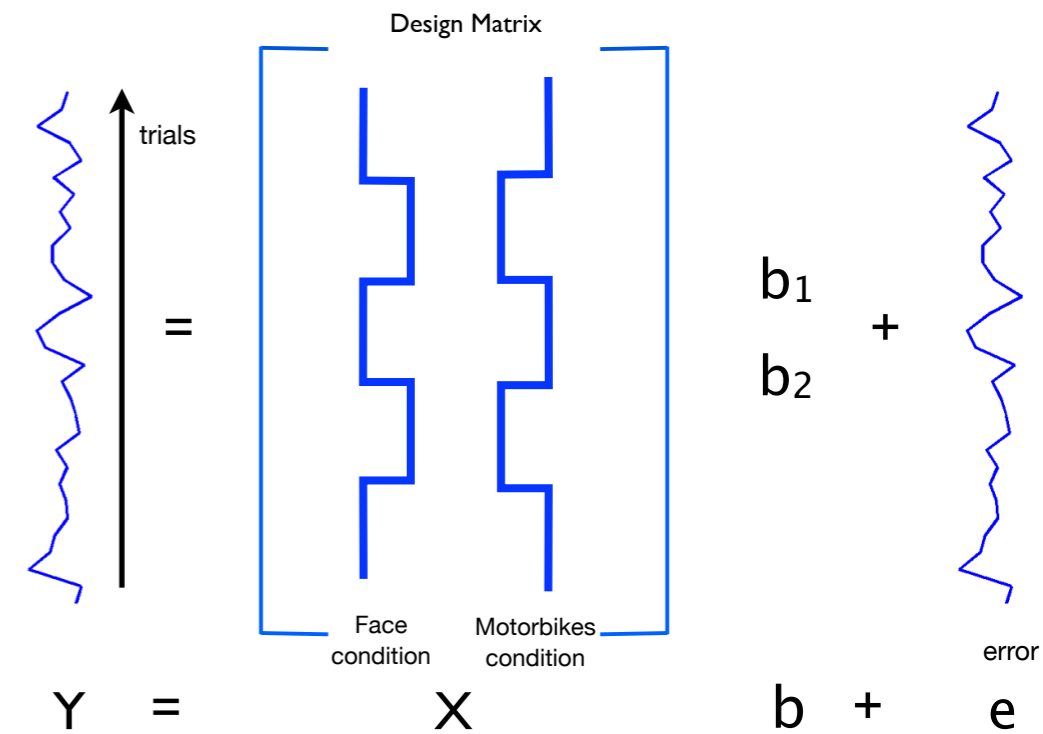
If P-Value  $<$  P-threshold then reject null hypothesis

P-threshold corresponds to False Positive Rate (FPR)

# Contrasts

A COntrast of Parameter Estimates (COPE) is a linear combination of parameter estimates, e.g.

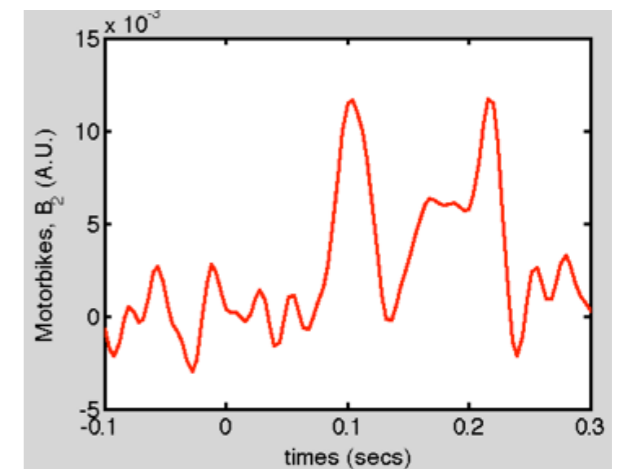
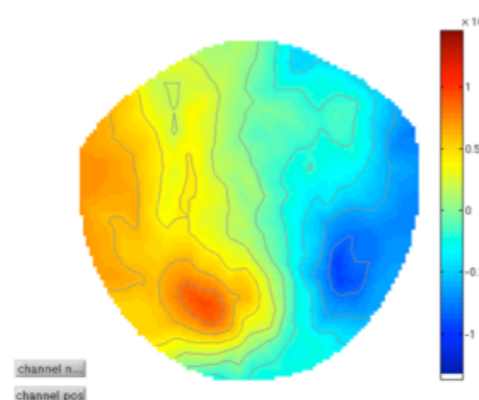
Contrast  $[0 \ 1]$  gives a COPE  $= 0 \times B_1 + 1 \times B_2$   
 $= B_2$



Test the null hypothesis that  $B_2=0$

*e.g. where in time and space is there significant positive\* activity in response to the motorbike condition?*

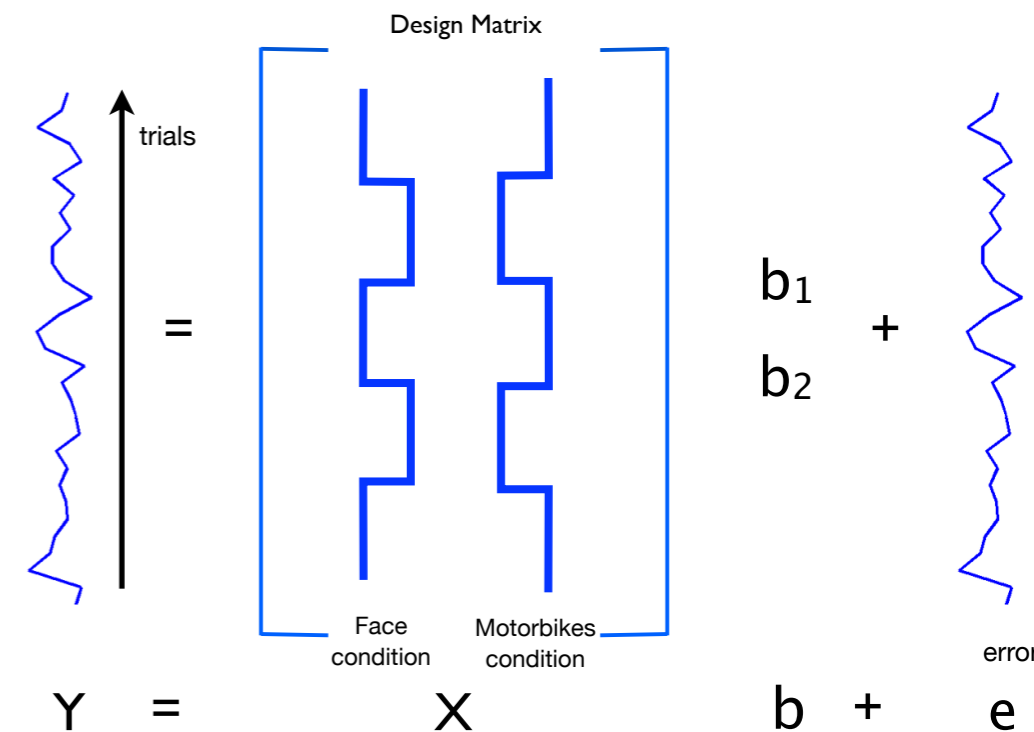
*\* as we are doing a one-tailed t-test*



# Contrasts

A COntrast of Parameter Estimates (COPE) is a linear combination of parameter estimates, e.g.

$$\text{Contrast } [1 \ -1] \text{ gives a COPE} = 1 \times B_1 - 1 \times B_2 \\ = B_1 - B_2$$



Test the null hypothesis that  $B_1 - B_2 = 0$

*e.g. where in time and space is there more\* activity in response to the faces than the motorbike condition?*

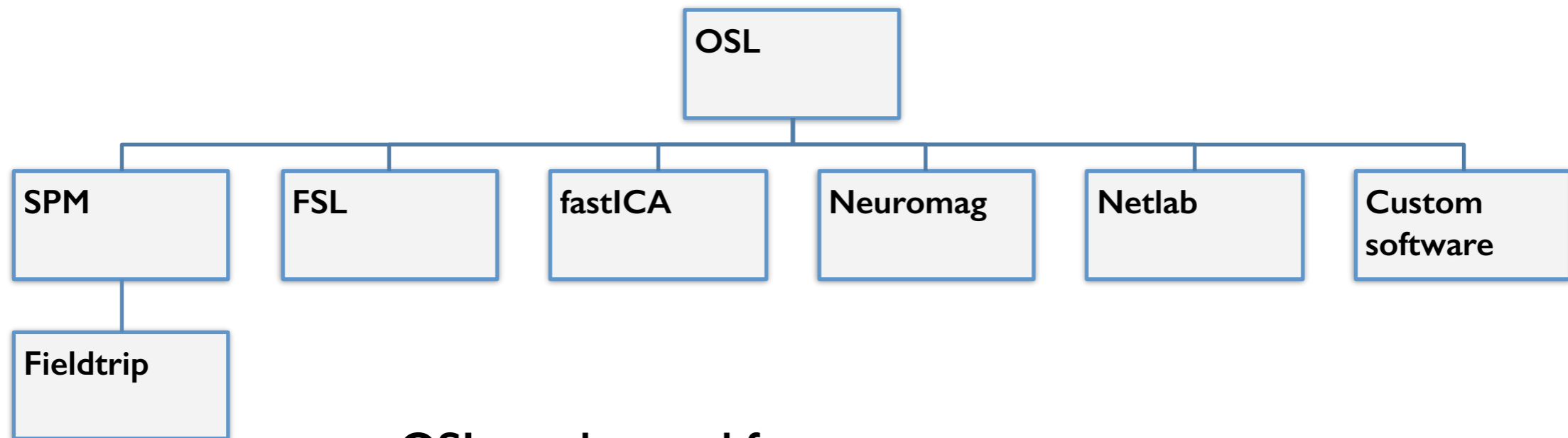
\* as we are doing a one-tailed t-test

# Other stuff the GLM can do

- Linear trends between conditions
  - ➔ plus quadratic, higher order trends
- Factorial designs (interaction effects)
- F-tests (combined explanatory power over multiple contrasts)
- Subject-wise GLMs at the **group level** (e.g. **patients vs controls**)
- See the FSL course FEAT/fMRI Preprocessing and Model-Based slides at:

<http://www.fmrib.ox.ac.uk/fslcourse>

# OHBA's Software Library



**OSL can be used for**

- **task (GLM) and rest (e.g. ICA) analyses**
- **preprocessing**
- **sensor space analysis**
- **source space analysis**
- **statistics**

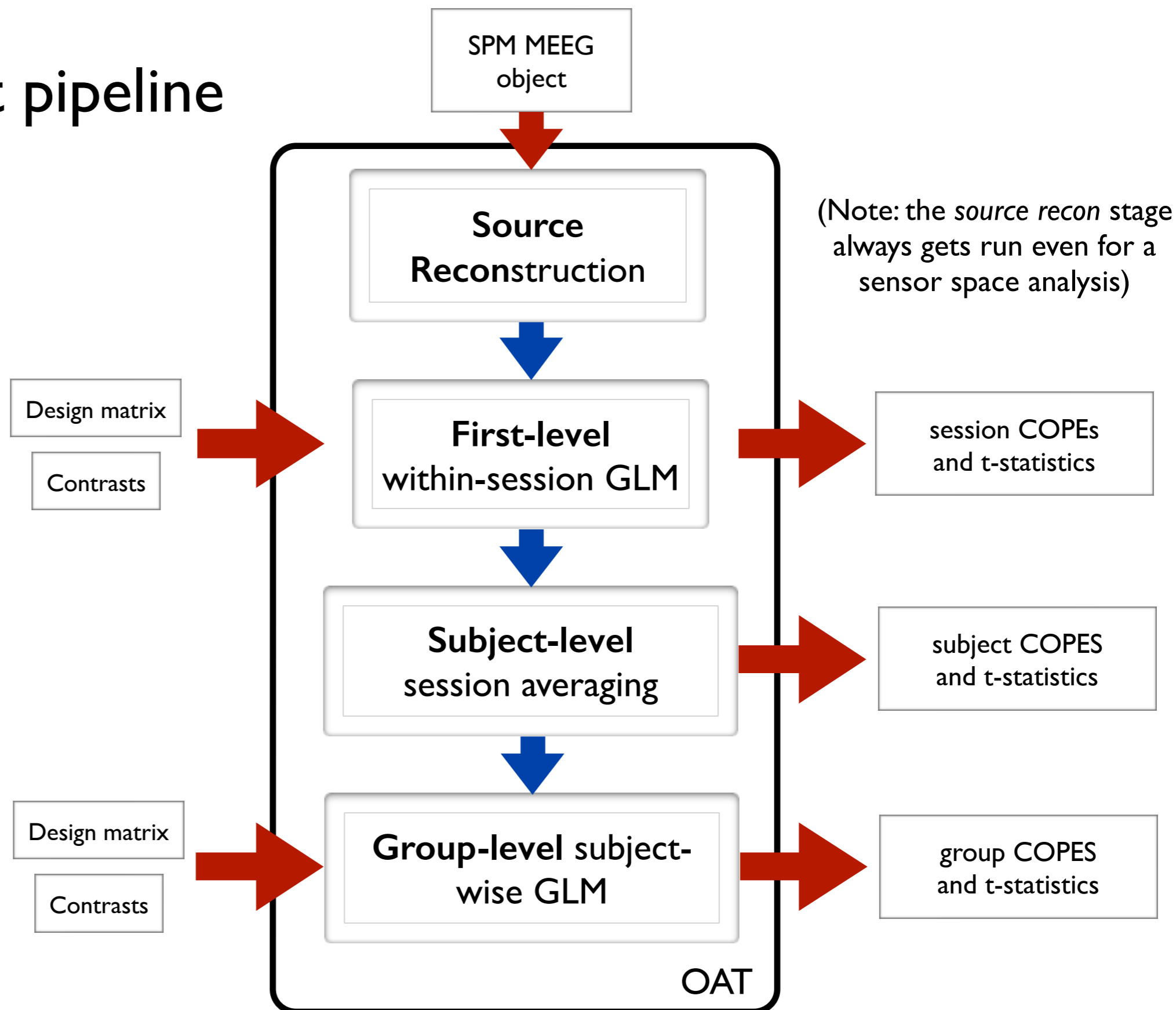


# OAT - OSL's (easy) Analysis Tool

- **Task-based analysis in:**
  - ➔ sensor space, or
  - ➔ source space (e.g. via beamforming)
- **In:**
  - ➔ in time-frequency domain (e.g. induced responses)
  - ➔ time domain (e.g. ERF-style), or
- **First-level (within-subject) analysis, using:**
  - ➔ trial-wise GLM on epoched data
  - ➔ time-wise GLM on continuous data
- **Group-level (between-subject) subject-wise GLM analysis**

# OAT Pipeline Stages

- 4 distinct pipeline stages:



# OAT Setup and Pipeline Stages

- Set some mandatory fields, and then use `osl_check_oat` call to setup an OAT struct:

➔ `oat = osl_check_oat(oat);`

- 4 distinct stages to the pipeline, with corresponding settings:

➔ `oat.source_recon`, e.g.

- `oat.source_recon.method='beamform';` % for beamforming
- `oat.source_recon.method='none';` % for a sensor space analysis

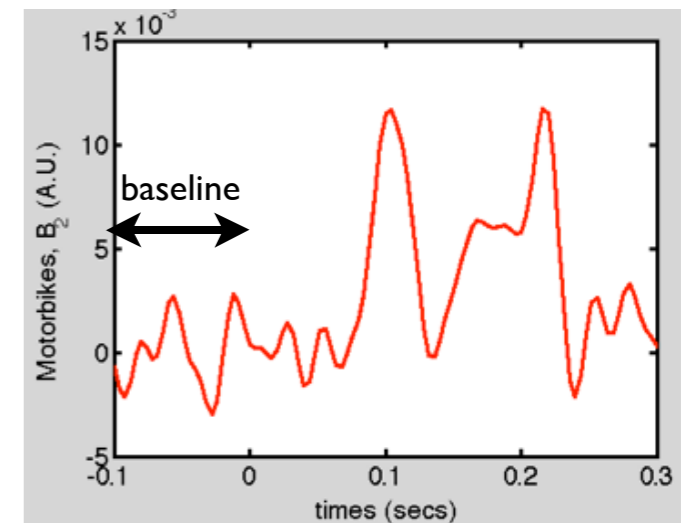
➔ `oat.first_level` (GLM within-session analysis)

➔ `oat.subject_level` (within-subject averaging)

➔ `oat.group_level` (GLM subject-wise analysis)

# Some `oat.first_level` settings

- baseline correction (BC), subtracts mean COPE in baseline time window (e.g.  $t < 0$ s)
- `oat.first_level.bc` specifies whether BC should be done for each contrast
  - ➔ BC is computed on the COPE time course
  - ➔ no need to do BC on differential contrasts (e.g.  $[1 \ -1]$  contrast)
  - ➔ *recommended* to do BC on main effect contrasts (e.g.  $[1 \ 0]$  contrast)



# Some `oat.first_level` settings

- Set time range and freq range using:
  - `oat.first_level.time_range` (for TF analyses need to make this time range is smaller than `oat.source_recon.time_range` to remove edge effects)
  - `oat.first_level.tf_freq_range`

# Some `oat.first_level` settings

- Set time range and freq range using:
  - `oat.first_level.time_range` (for TF analyses need to make this time range is smaller than `oat.source_recon.time_range` to remove edge effects)
  - `oat.first_level.tf_freq_range`
- To do an ERF analysis set `oat.first_level.tf_method='none'`
- To do a Hilbert Time-Frequency (TF) analysis set `oat.first_level.tf_method='hilbert'`
- To do a Morlet Wavelet Time-Frequency (TF) analysis set `oat.first_level.tf_method='morlet'`
- For TF analyses set the number of frequency bins using `oat.first_level.tf_num_freqs=10`

# Running OAT

- Use `osl_run_oat` to run an OAT:

➔ `oat=osl_run_oat(oat);`

- This runs the stages specified in `oat.to_do`,  
e.g.:

➔ `oat.to_do=[1 1 0 0];` only runs `source_recon` and first-level stages

# OAT output

- Results are stored in the directory specified in `oat.source_recon.dirname`, with a `'oat'` suffix
- This directory includes a `*.mat` file, can load this into Matlab with:  
`oat=osl_load_oat(oat);`

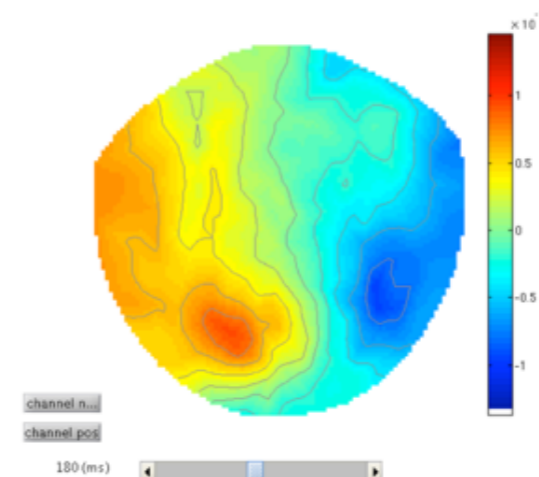


# OAT output

- Results are stored in the directory specified in `oat.source_recon.dirname`, with a `.oat` suffix
- This directory includes a `*.mat` file, can load this into Matlab with:  
`oat=osl_load_oat(oat);`
- This loads in a struct containing the settings used and the filenames of the outputs for each stage of the pipeline:
  - ➔ `oat.source_recon.results_fnames`
  - ➔ `oat.first_level.results_fnames`
  - ➔ `oat.subject_level.results_fnames`
  - ➔ `oat.group_level.results_fnames`
- These can be loaded into Matlab, e.g. to load session 2's first level results use the call:
  - ➔ `res=osl_load_oat_results(oat, oat.first_level.results_fnames{2})`

# Viewing OAT output

- It is highly recommended that you inspect *oat.results.report* (an HTML page), to ensure that OAT has run successfully (See the practical)
- In sensor space, use:
  - Use *osl\_stats\_multiplotER* and *osl\_stats\_multiplotTFR* to call Fieldtrip interactive topoplots
  - The two orientations of the *MEGPLANARs* are combined (in the *first\_level* stage) by rectifying and adding



# Practical

- 1) Sensor space trial-wise GLM using OAT on **epoched** data:
  - a) Time-domain (ERF) analysis
  - b) Time-frequency (induced response) analysis
- 2) Sensor space time-wise GLM using OAT on **continuous** data.

# Finally

- If you end up using OSL for your own data analysis then please get in touch with me
- Look at and use the OSL Wiki!
  - <https://sites.google.com/site/ohbaosl/>
  - sign up for OSL email list