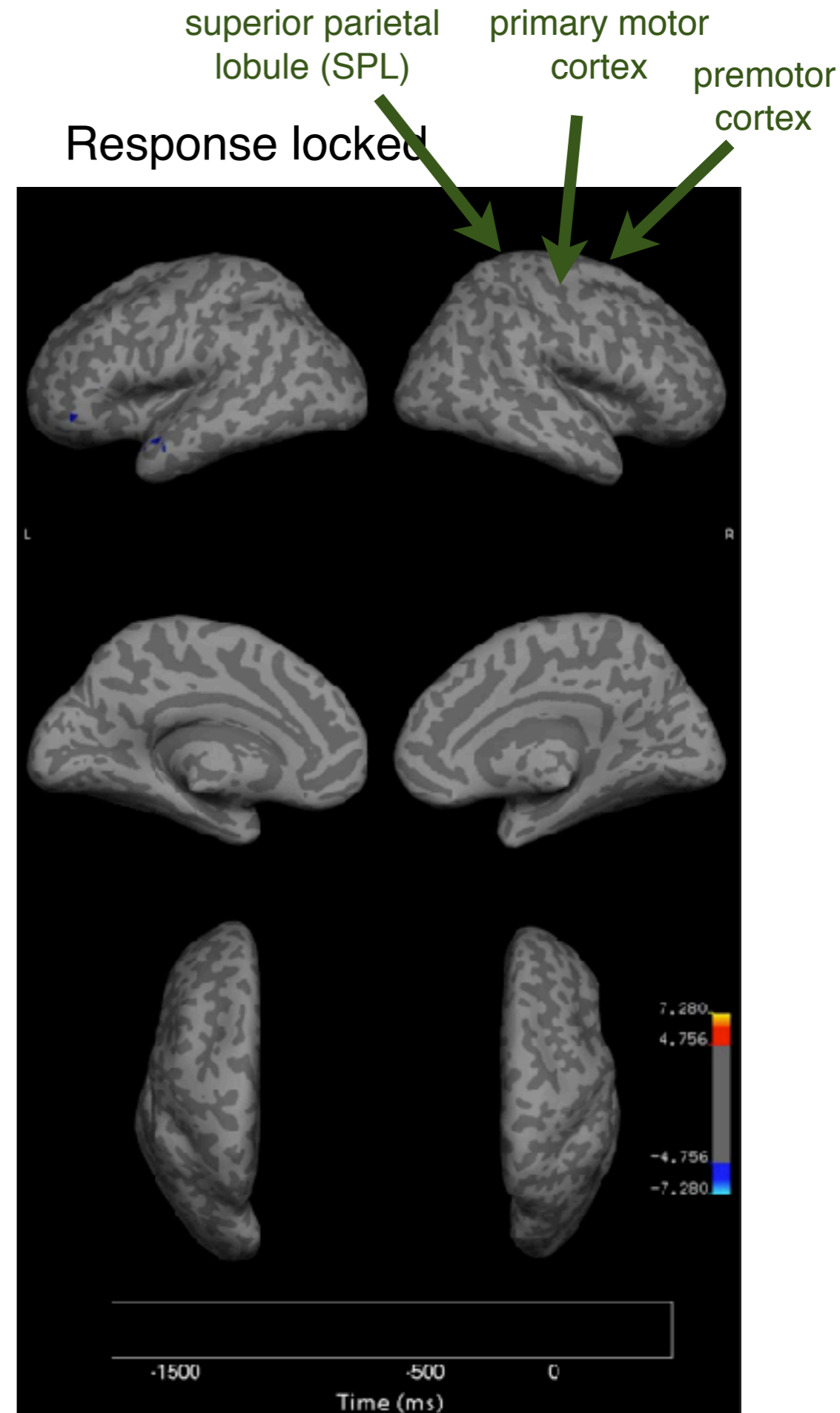
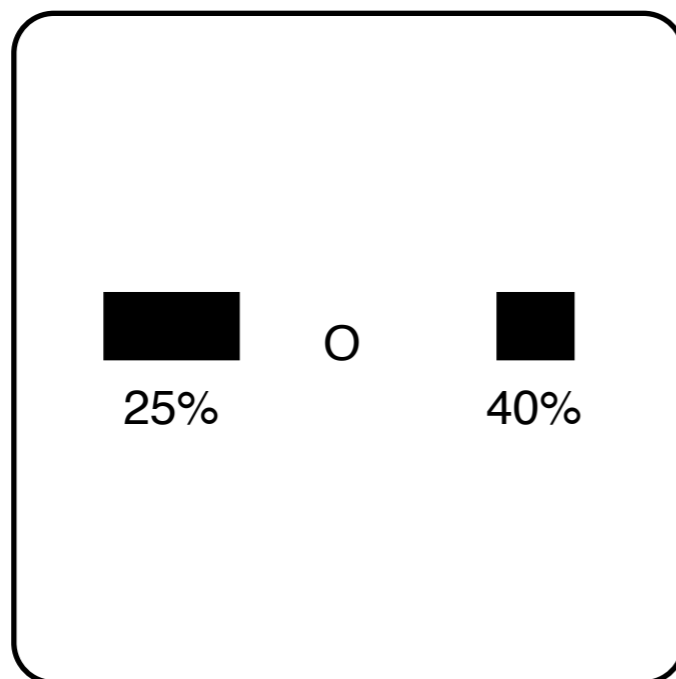


# Sensor Space Analysis

OHBA MEG Analysis Workshop

- Induced analysis of the decision making period:
  - **source reconstruction**
  - *epoching*: time-locked to when the response is given
  - compute the **average evoked power** (the induced response, ERD/ERS) from 1-12Hz
  - **group averaged** over 30 subjects



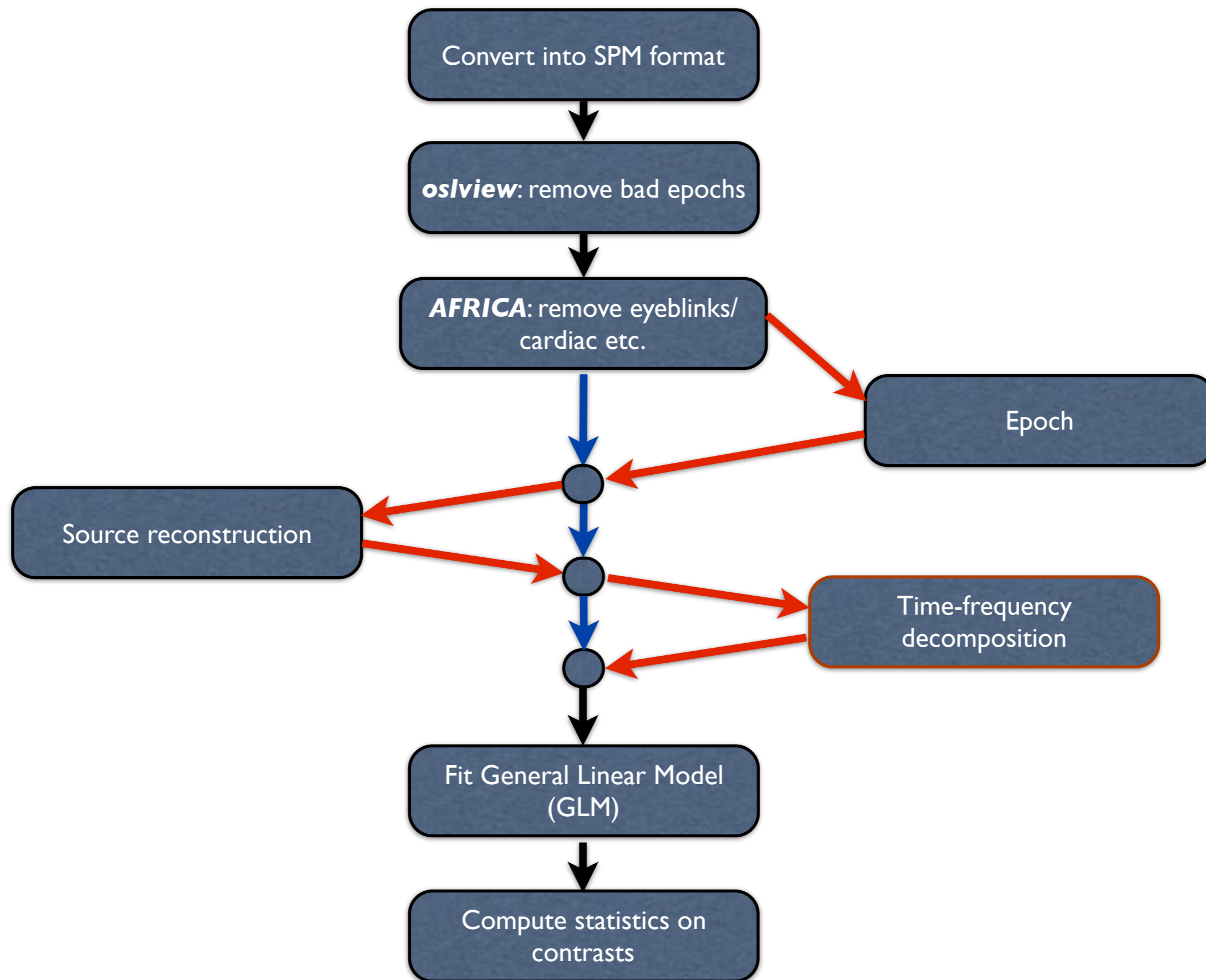
Hunt et al., Nature Neuroscience, 2012.

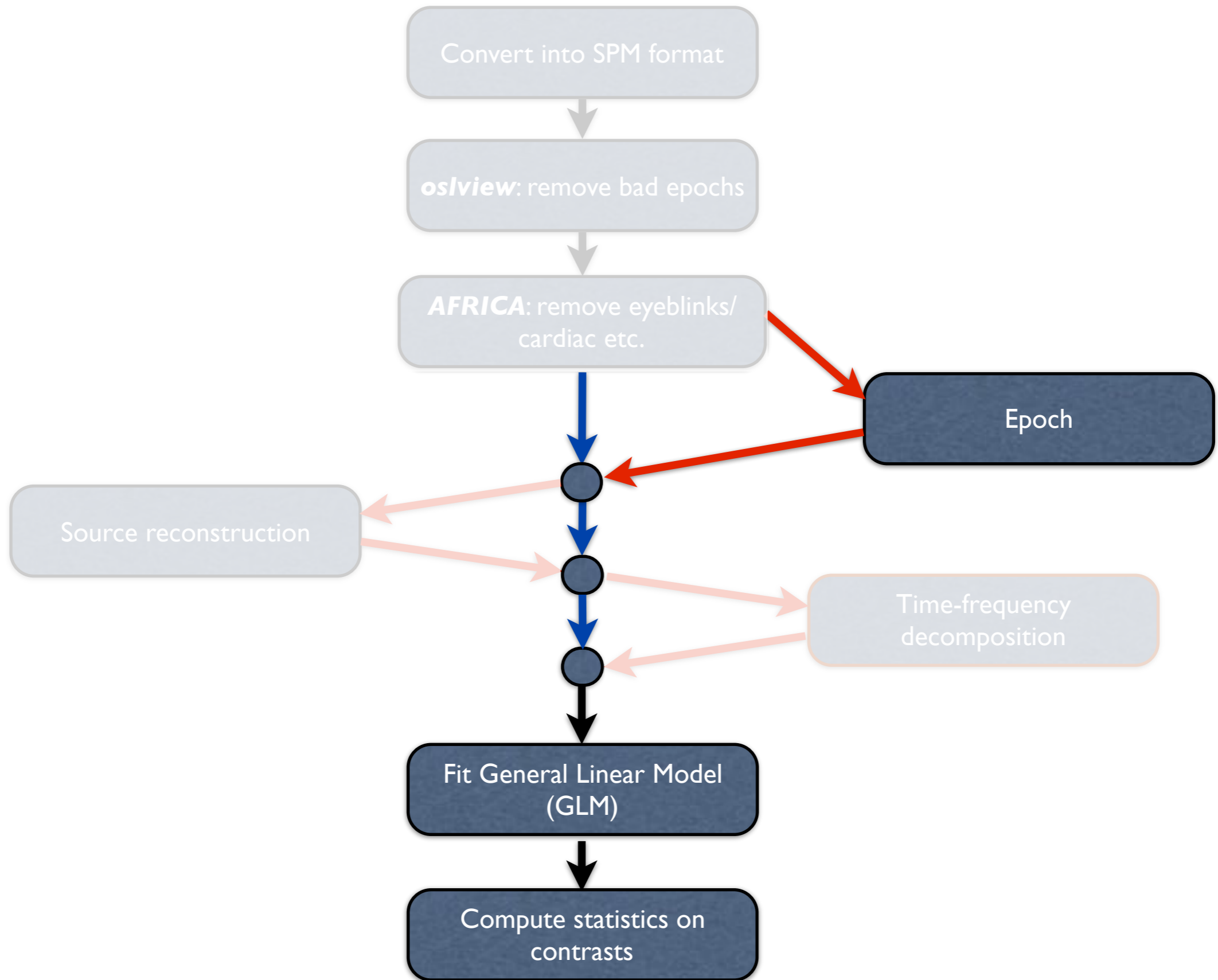
# Talk Outline

- Analysing epoched task data in sensor space
- OSL (OHBA's Software Library):
  - OAT (OSL's Analysis Tool)

# Epoched Data Example

- **Faces versus motorbikes**
  - ➔ 240 trials (epochs) of presenting pictures of faces
  - ➔ 120 trials (epochs) of presenting pictures of motorbikes
- **We want to compare the responses time-locked to stimulus presentation (i.e. the Event-Related Fields (ERFs))**

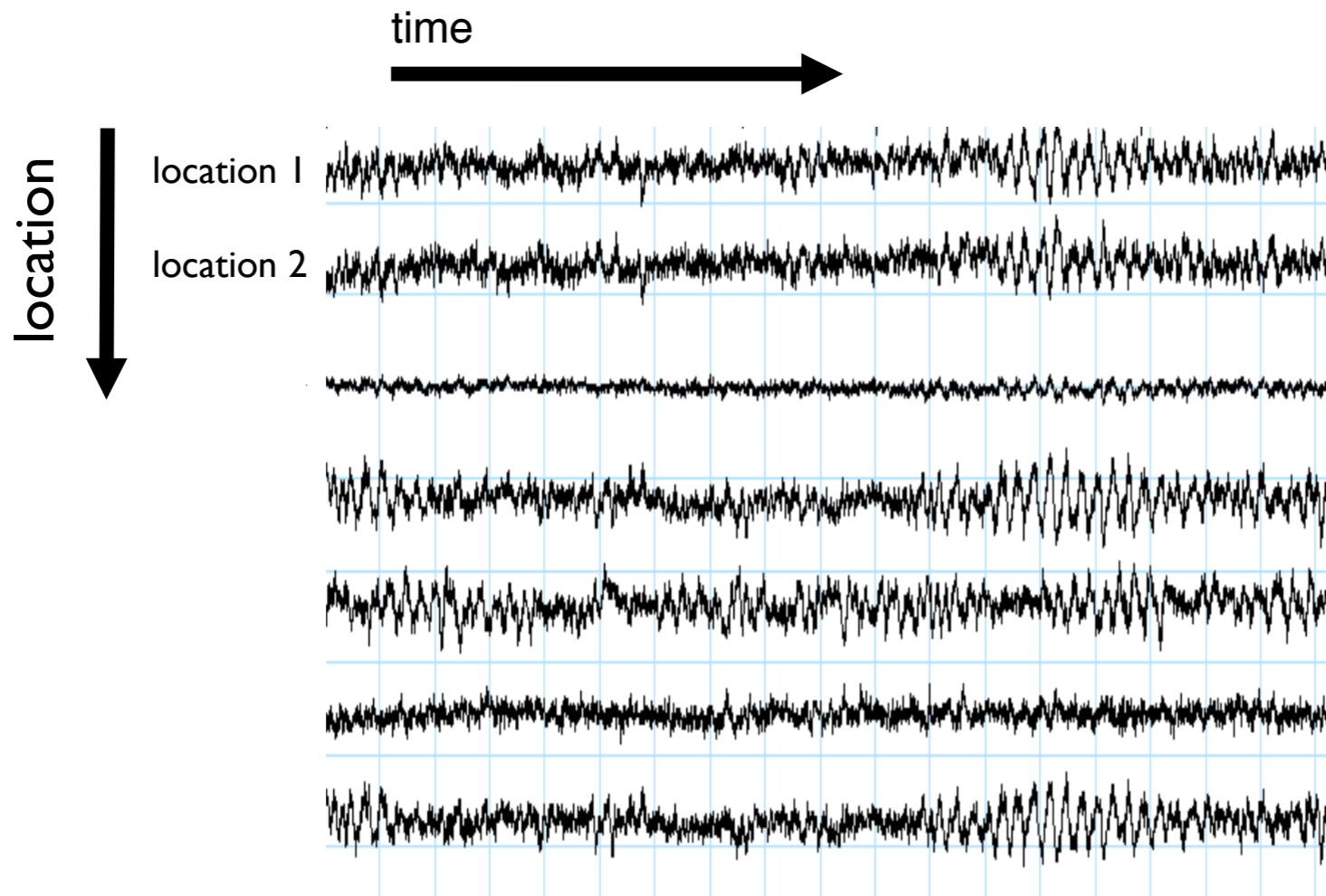




# Epoching and ERFs

Epoching takes in source or sensor data:

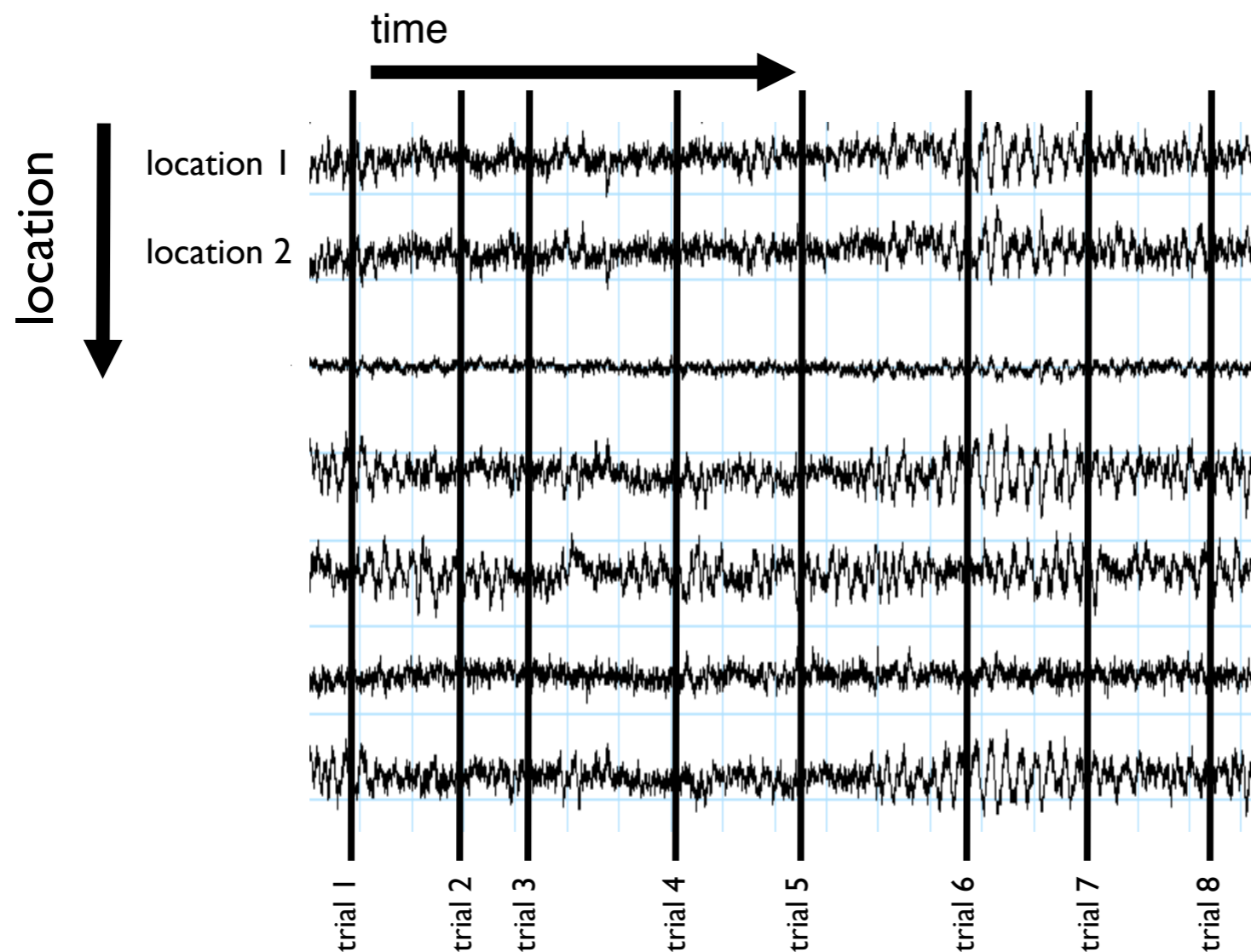
*locations x timepoints*



# Epoching and ERFs

Epoching takes in source or sensor data:

*locations x timepoints*



I. Identify when trial events occurred (e.g. the time of stimulus presentation in each trial)

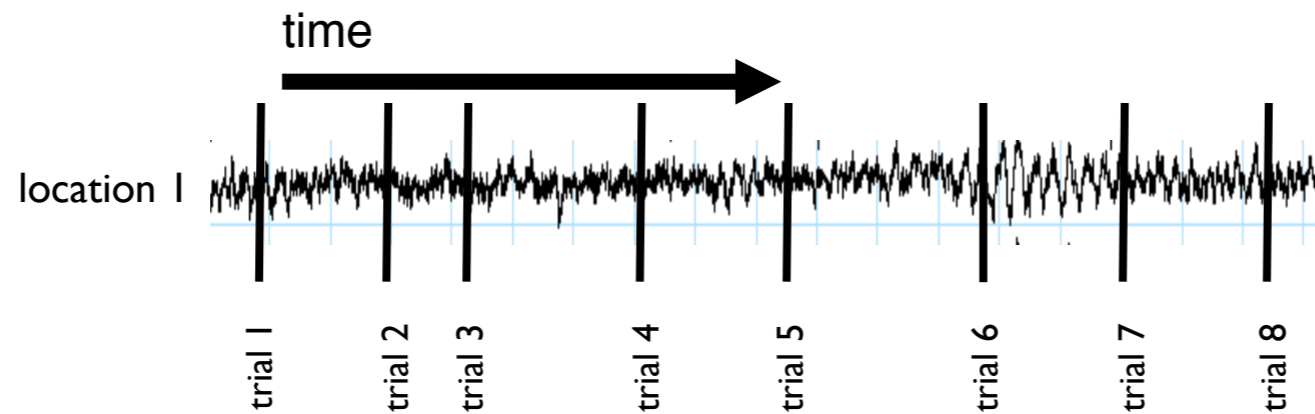


# Epoching and ERFs

Epoching takes in source or sensor data:

*locations x timepoints*

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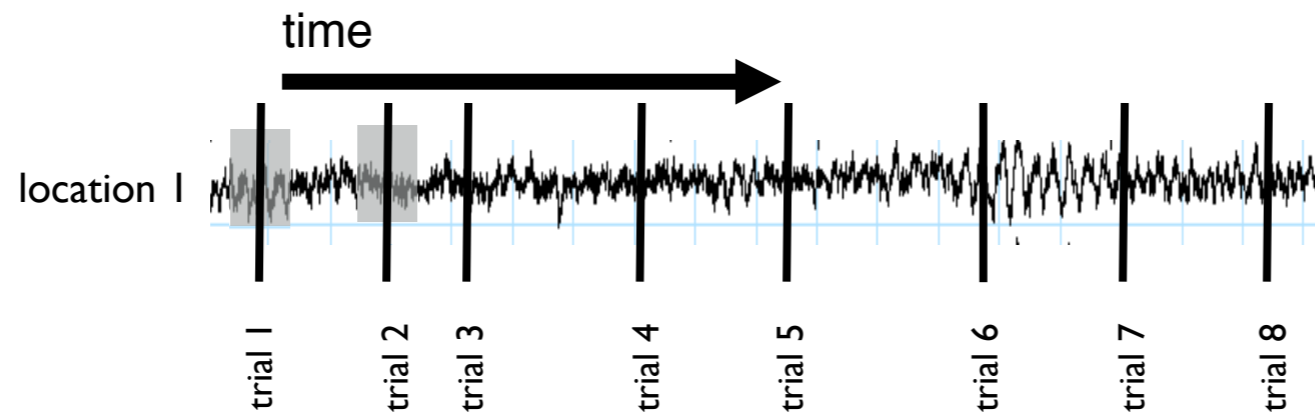


# Epoching and ERFs

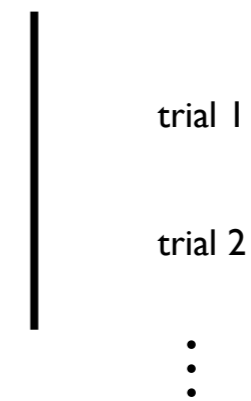
Epoching takes in source or sensor data:

*locations x timepoints*

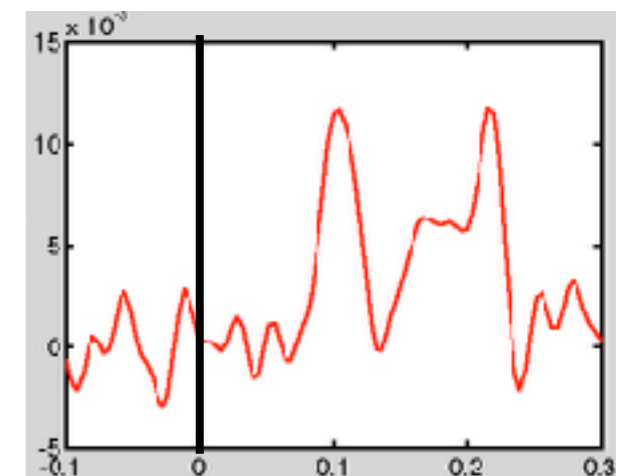
1. Identify when trial events occurred (e.g. the time of stimulus presentation in each trial)



2. Extract time-locked “epochs” of data



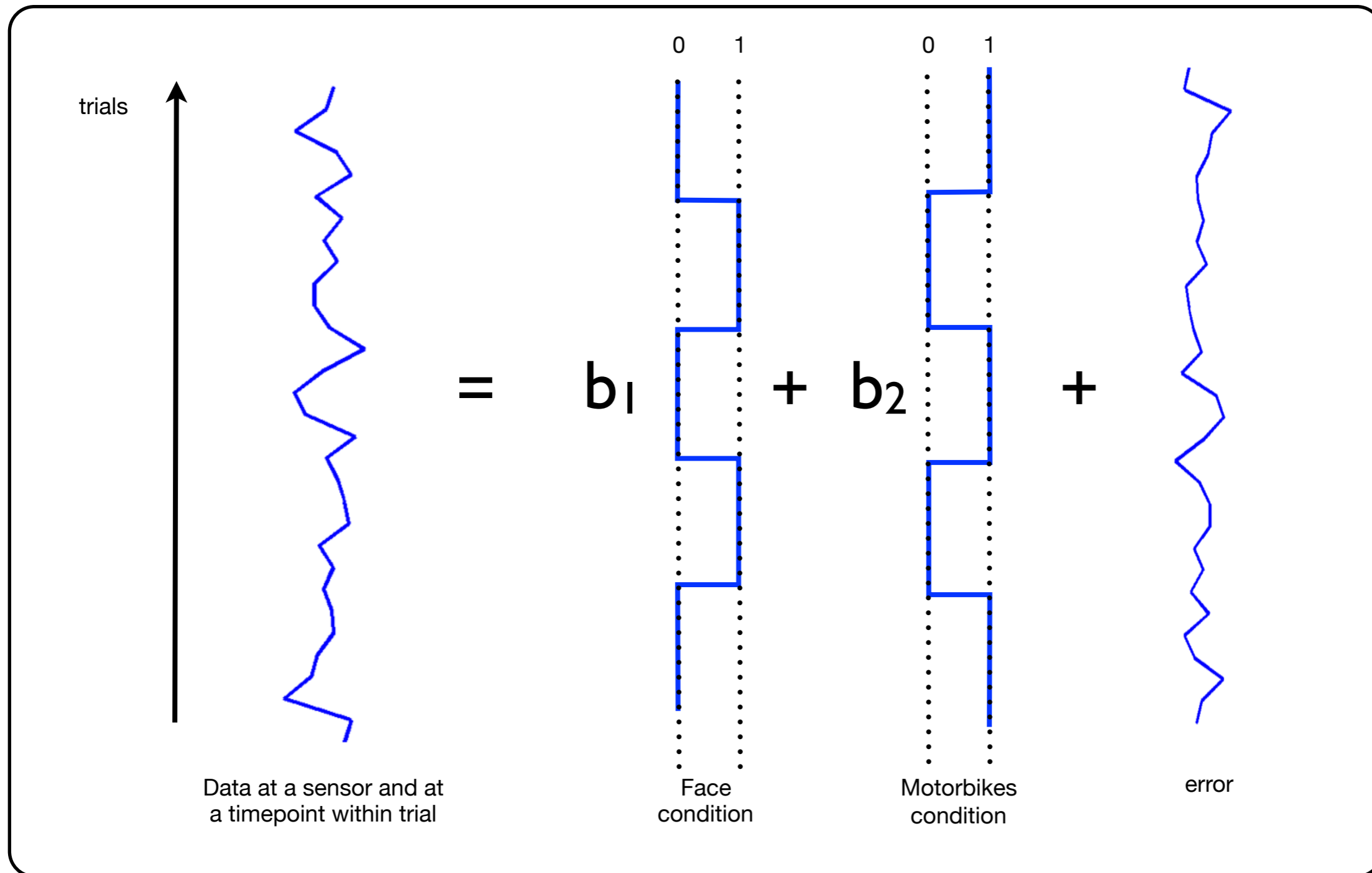
3. Average over all trials to compute an average stimulus response, known as an ERF (Event Related Field)



time-within-trial (s)

# Trial-wise multiple regression

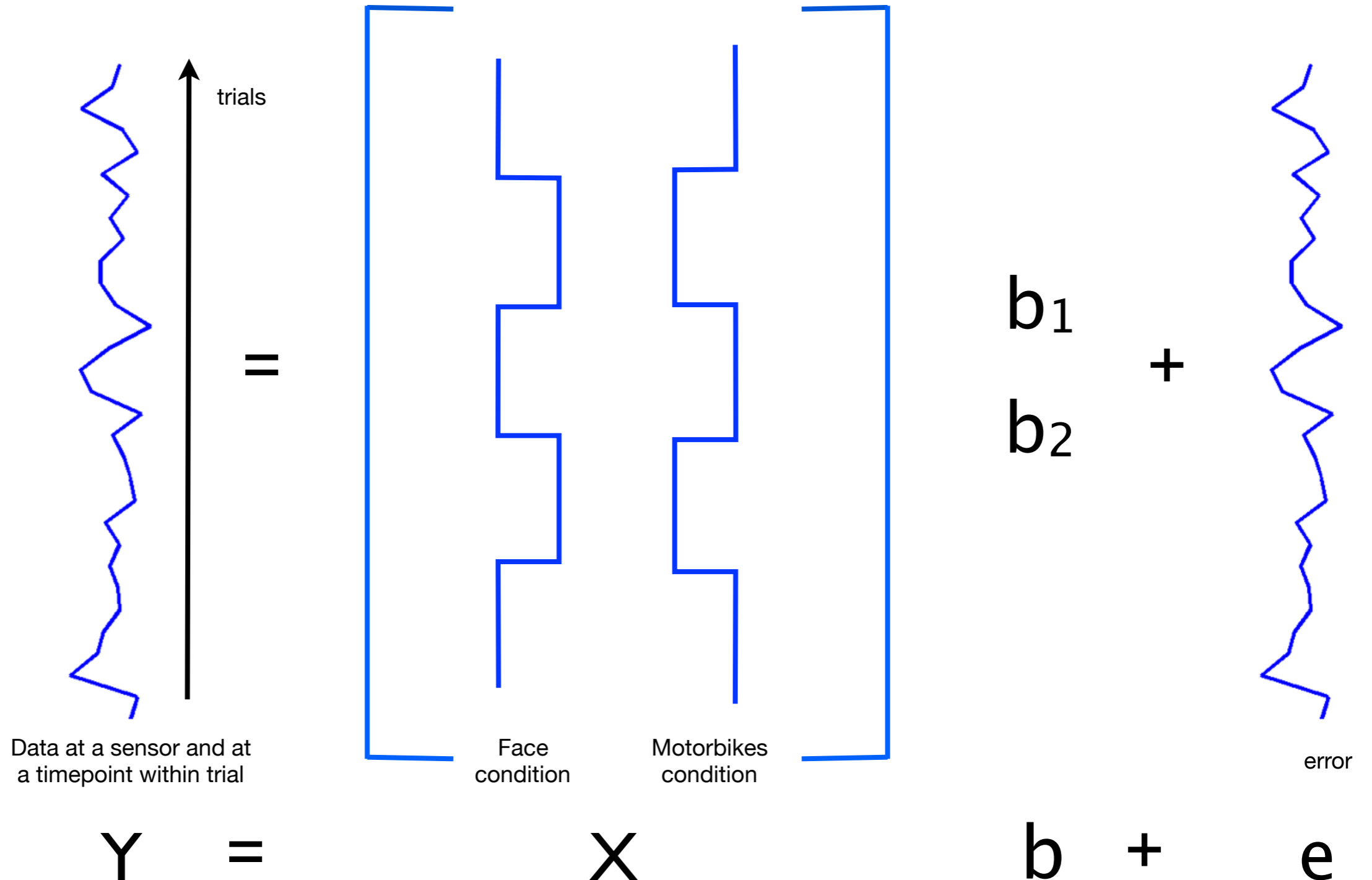
ERFs can be also computed using separate multiple regressions at each sensor and timepoint



# Trial-wise GLM

More formally we fit a separate General Linear Model (GLM) at each sensor and timepoint

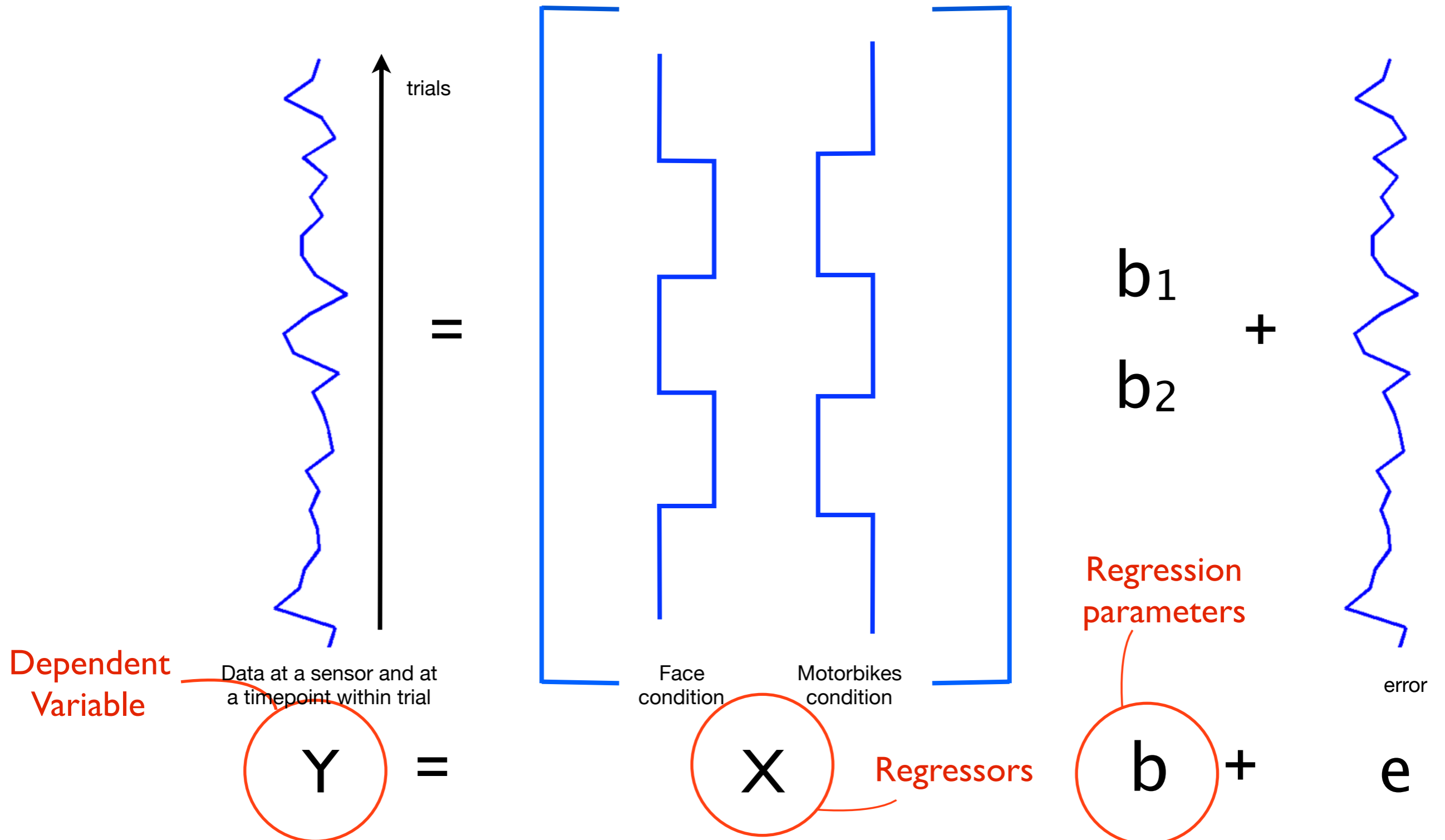
## Design Matrix



# Trial-wise GLM

More formally we fit a separate General Linear Model (GLM) at each sensor and timepoint

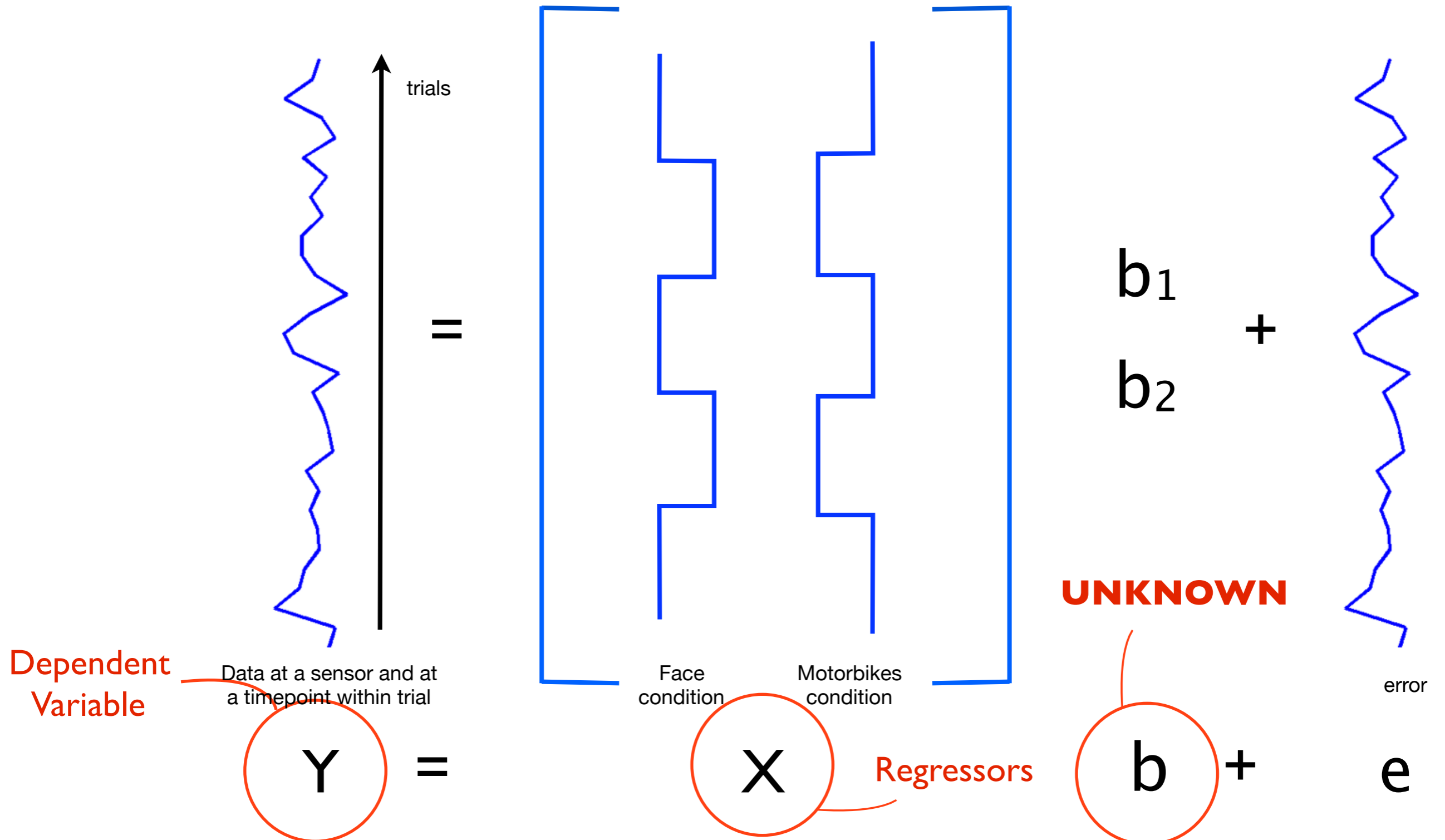
## Design Matrix



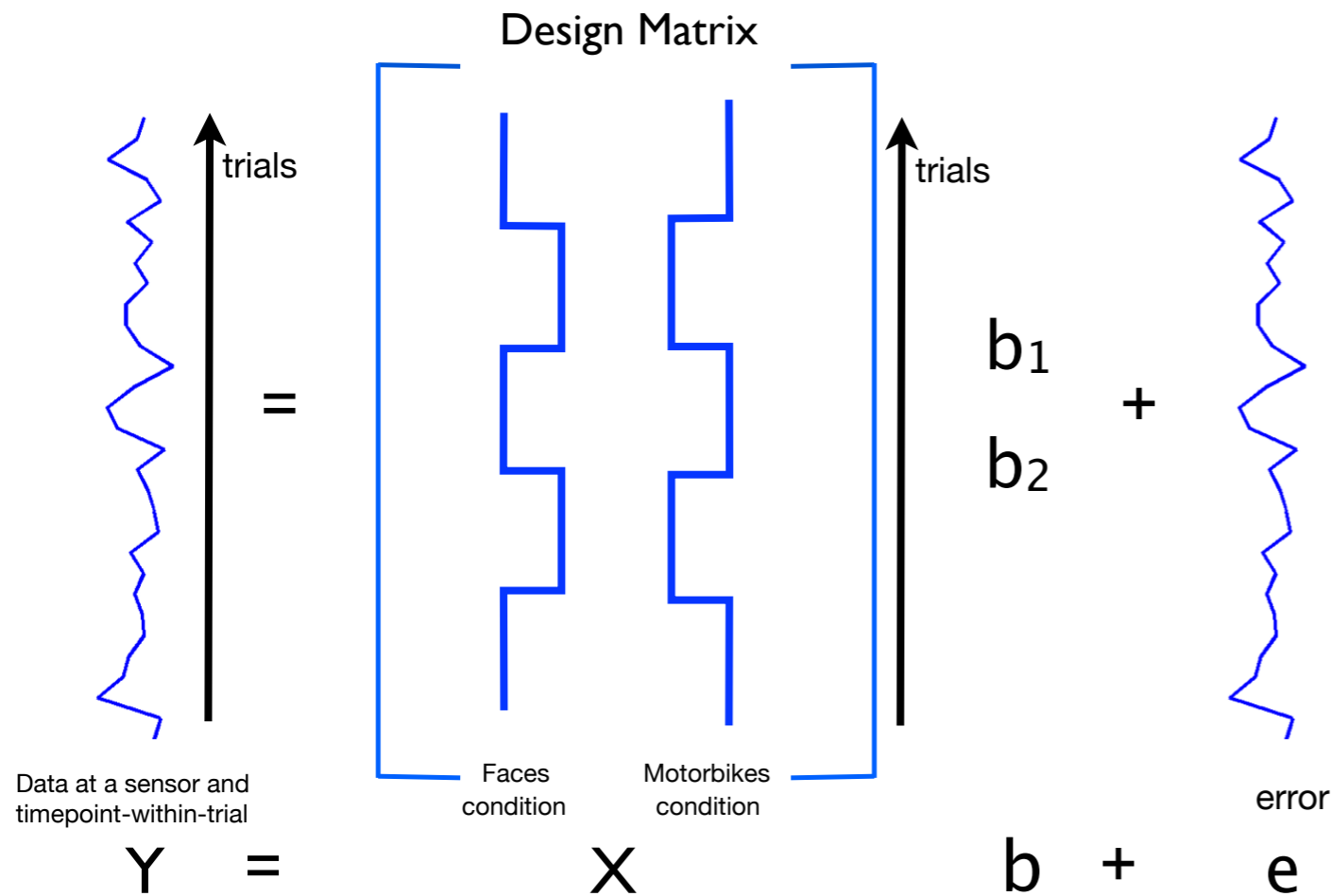
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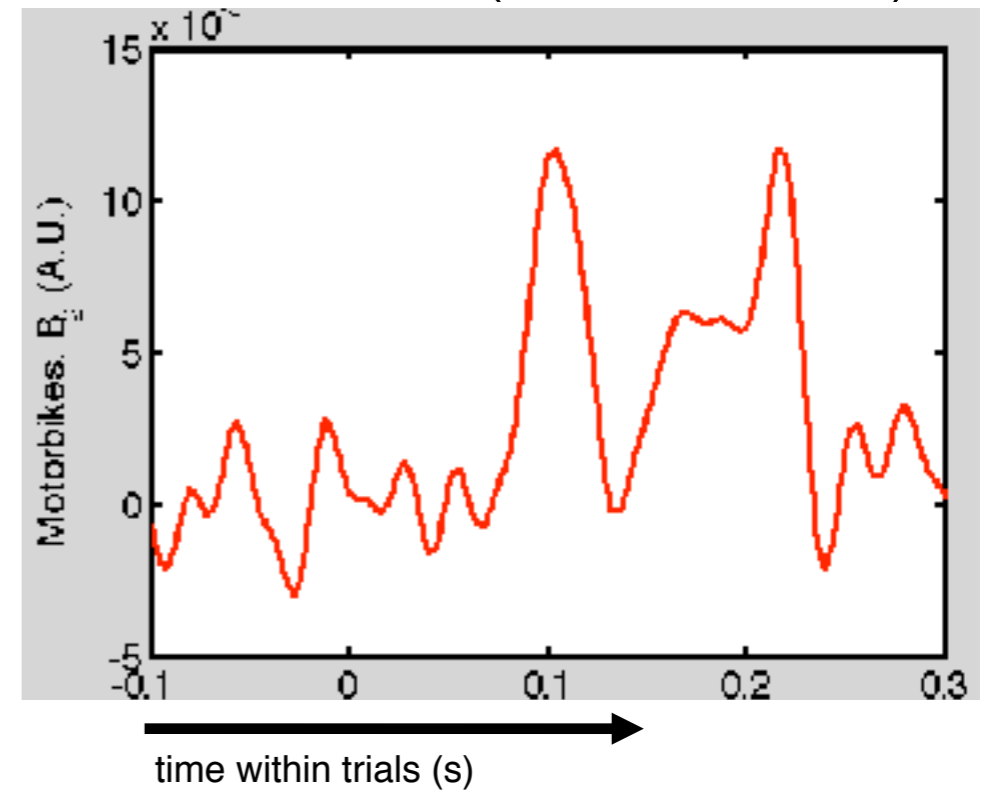
## Design Matrix



# Fitting over time = ERF



Motorbikes ( $B_2$ ) at a sensor near the visual cortex (motorbike ERF)



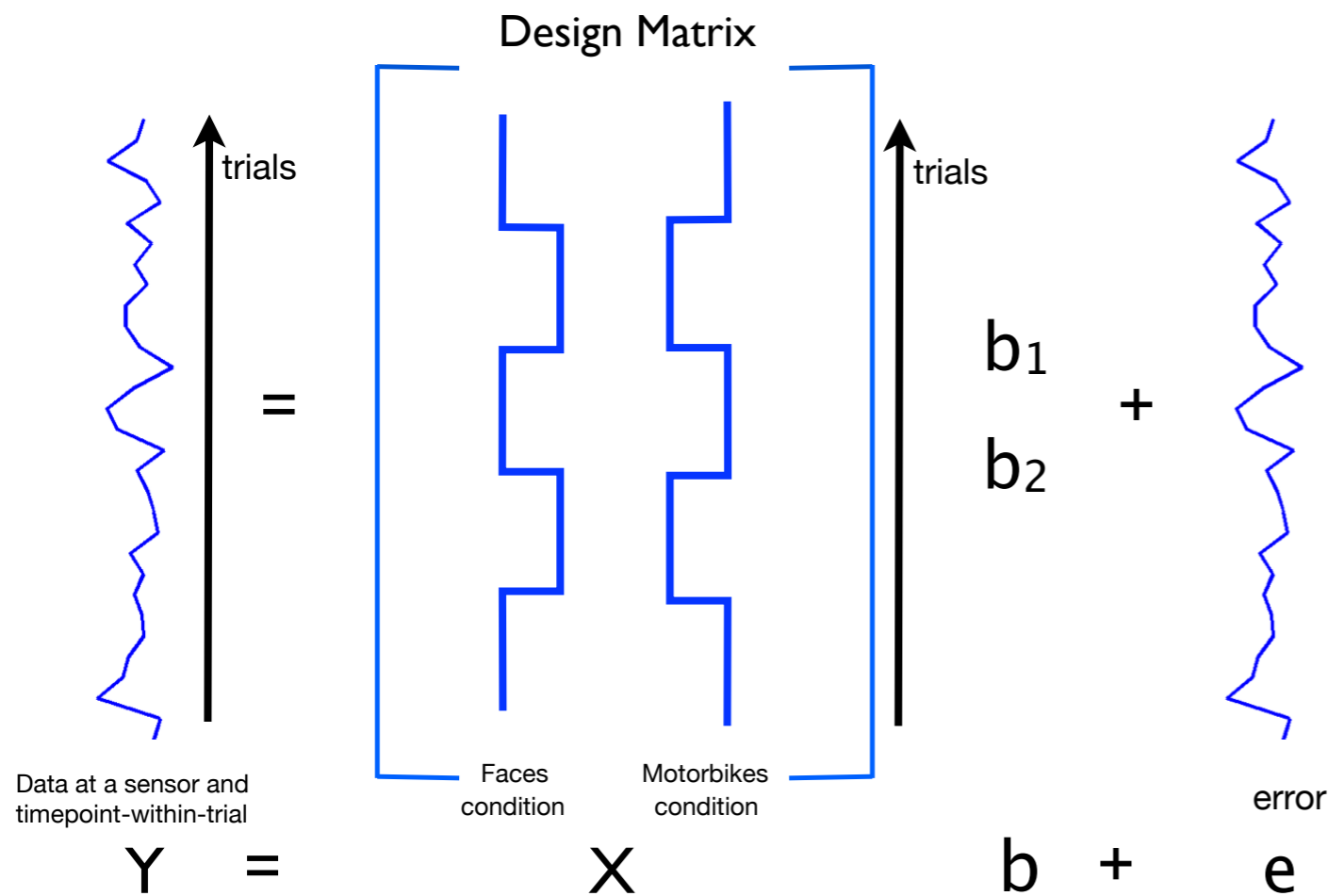
Repeat for all timepoints within-trial at a sensor

$$Y = Xb + e$$

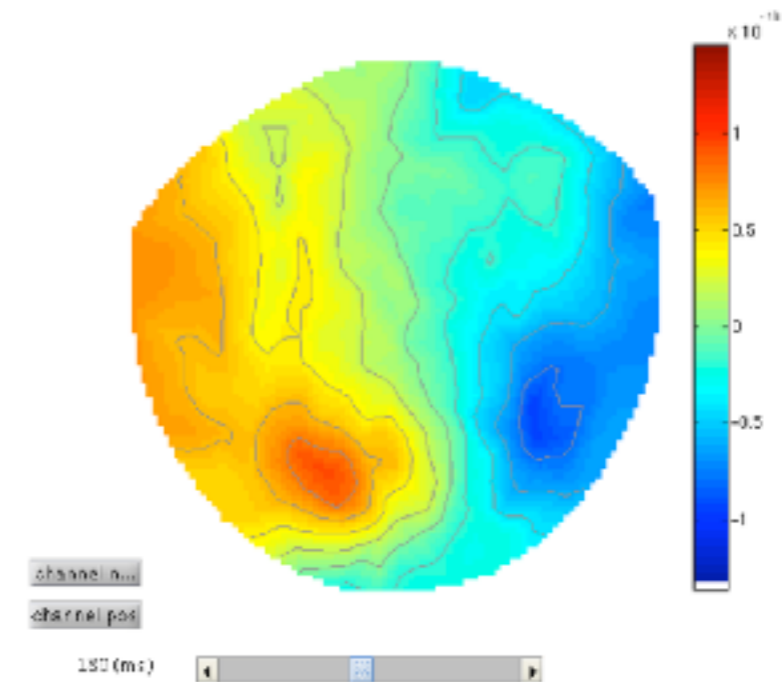


$B$  are the Parameter Estimates (PEs) of  $b$

# Fitting over sensors



Motorbikes ( $B_2$ ) at 100ms post-stimulus



Repeat for all sensors at a time-within-trial

$$Y = Xb + e$$

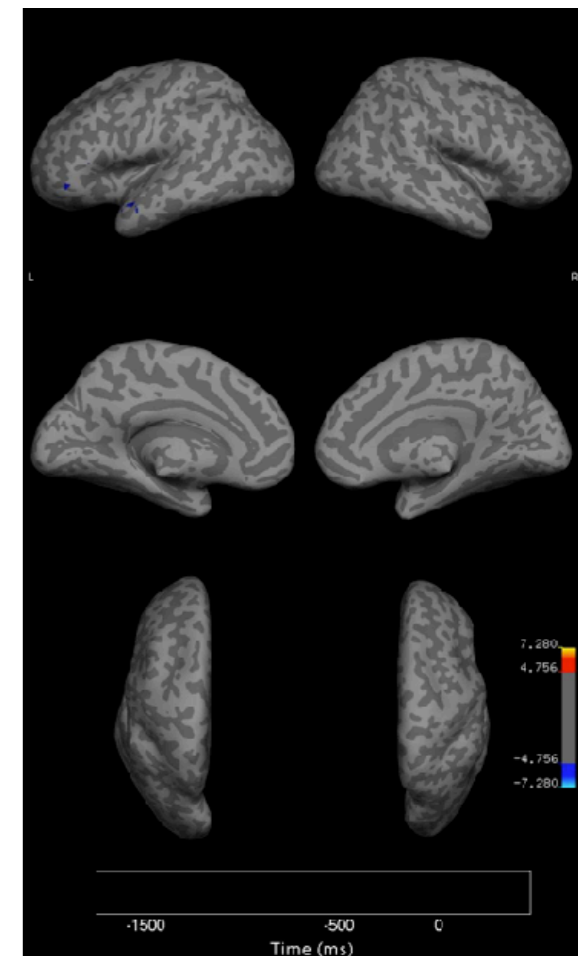
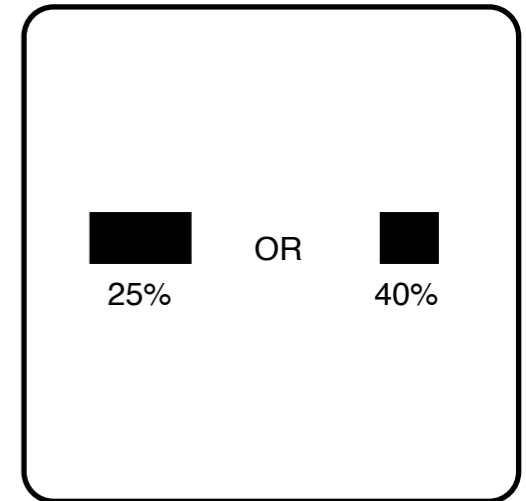
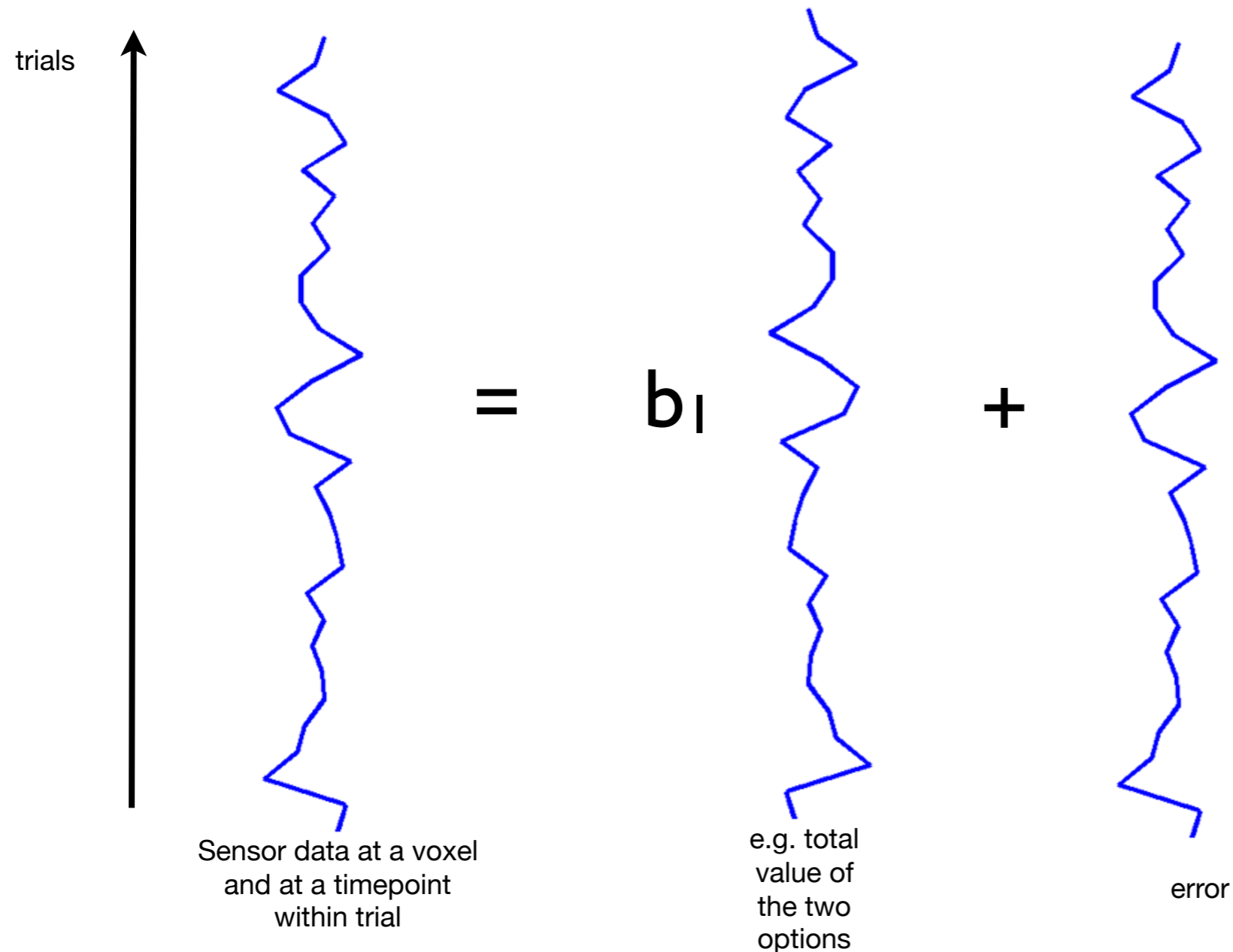


$B$  are the Parameter Estimates (PEs) of  $b$



# GLM

Note that the GLM is a general framework, e.g. in which we can also fit continuous variables:



# Other stuff the GLM can do

- Continuous (e.g. behavioural) variables
- Time-frequency (induced response) analysis
- Linear, and higher order, trends between conditions
- Factorial designs (interaction effects)
- F-tests (combined explanatory power over multiple contrasts)
- Subject-wise GLMs at the [group level \(e.g. patients vs controls\)](#)
- See the FSL course FEAT/FMRI Preprocessing and Model-Based slides at:

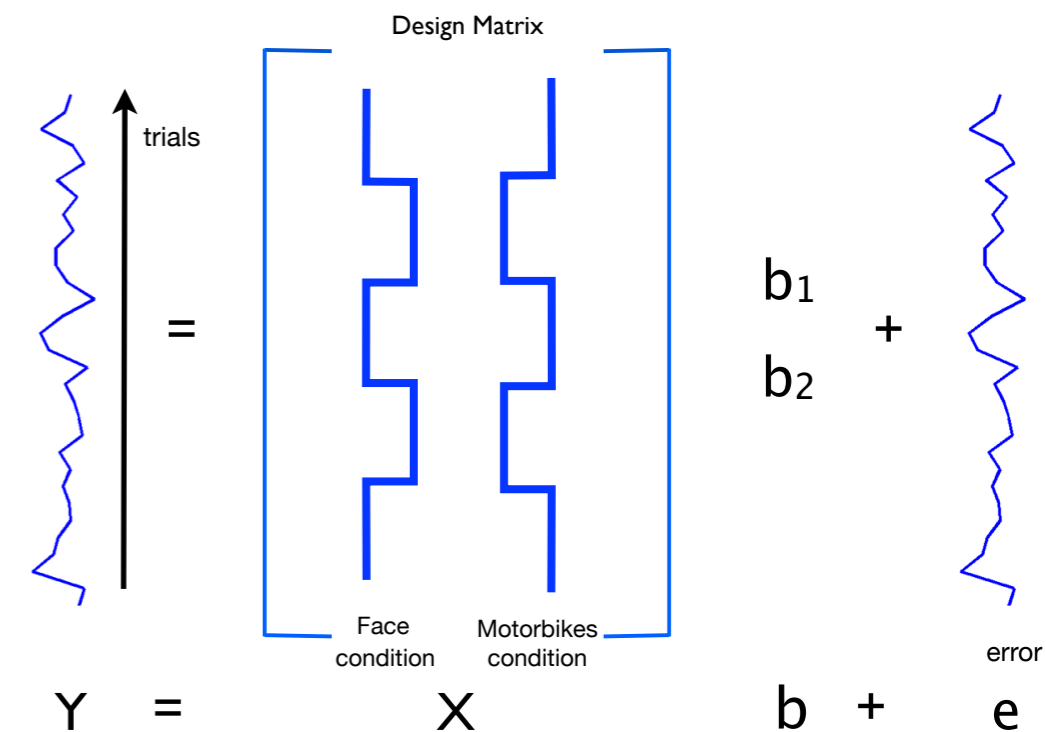
<http://www.fmrib.ox.ac.uk/fslcourse>

# Contrasts

A COntrast of Parameter Estimates (COPE) is a linear combination of the regression parameter estimates, e.g.

Contrast  $[1 \ 0]$  gives a COPE  $= 1 \times B_1 + 0 \times B_2$   
 $= B_1$

Contrast  $[1 \ -1]$  gives a COPE  $= 1 \times B_1 - 1 \times B_2$   
 $= B_1 - B_2$

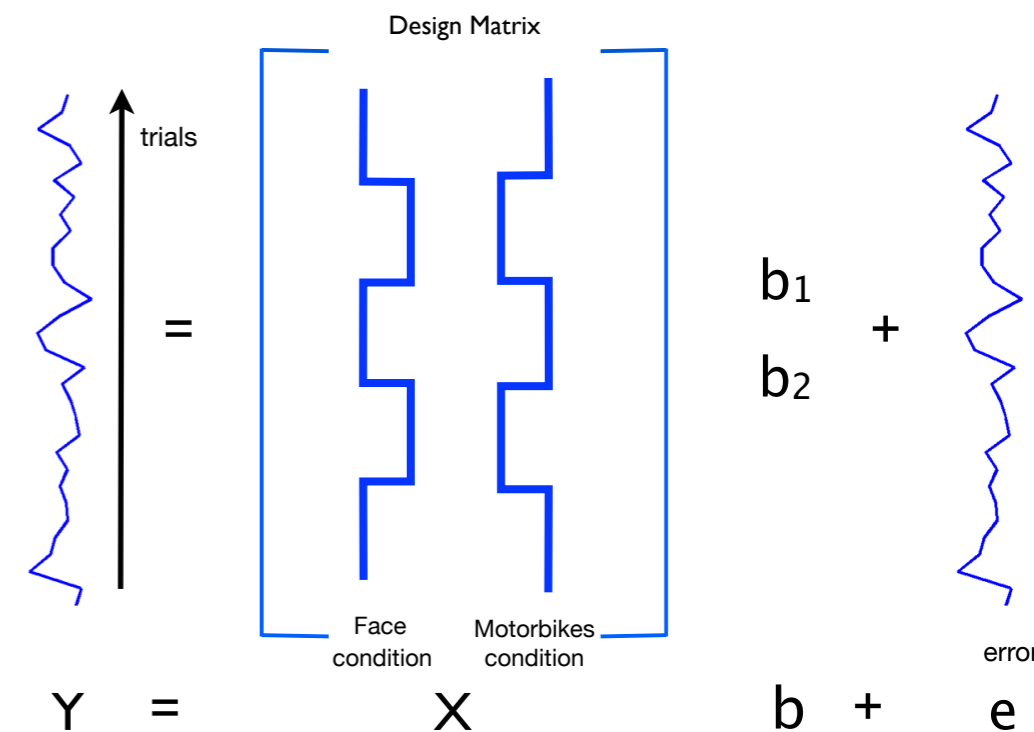


# Contrasts

A COntrast of Parameter Estimates (COPE) is a linear combination of the regression parameter estimates, e.g.

Contrast [1 0] gives a COPE =  $1 \times B_1 + 0 \times B_2$   
 $= B_1$

Contrast [1 -1] gives a COPE =  $1 \times B_1 - 1 \times B_2$   
 $= B_1 - B_2$



Use a t-test to test the null hypothesis that  $COPE=0$ :

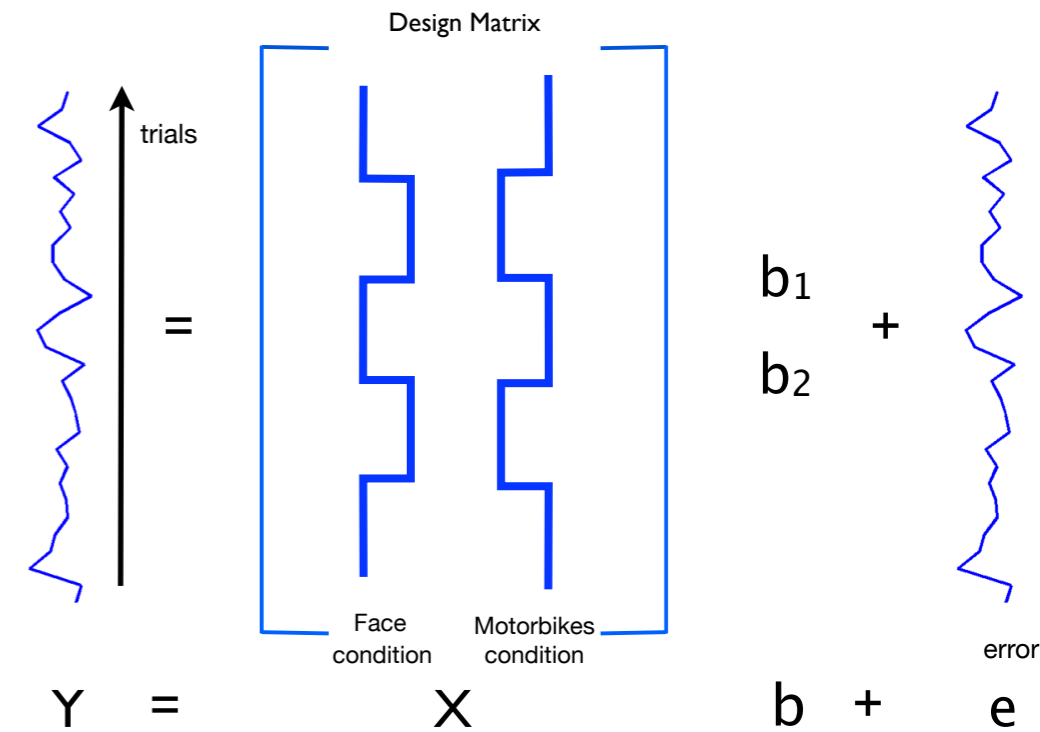
t-statistic:

$$t = \frac{COPE}{std(COPE)}$$

# Contrasts

A COntrast of Parameter Estimates (COPE) is a linear combination of parameter estimates, e.g.

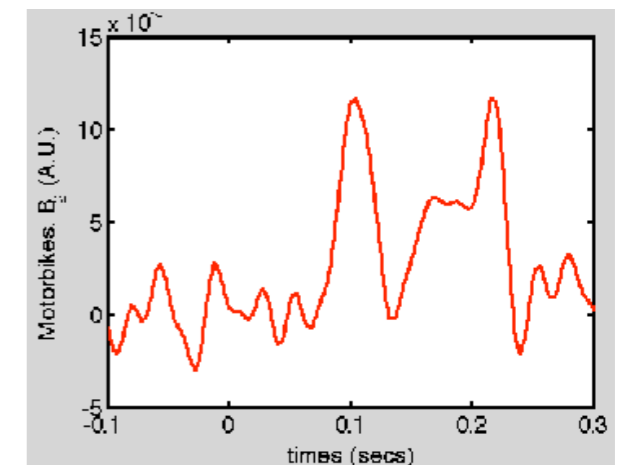
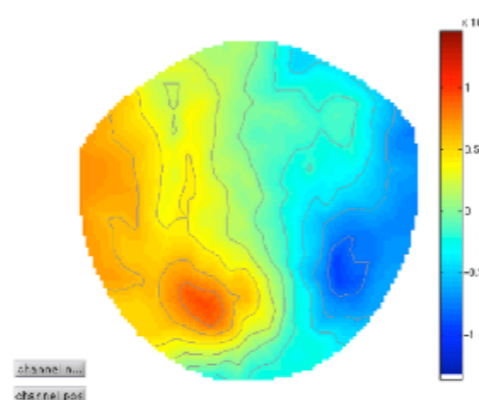
Contrast  $[0 \ 1]$  gives a COPE  $= 0 \times B_1 + 1 \times B_2$   
 $= B_2$



Test the null hypothesis that  $B_2=0$

**e.g. where in time and space is there significant positive\* activity in response to the motorbike condition?**

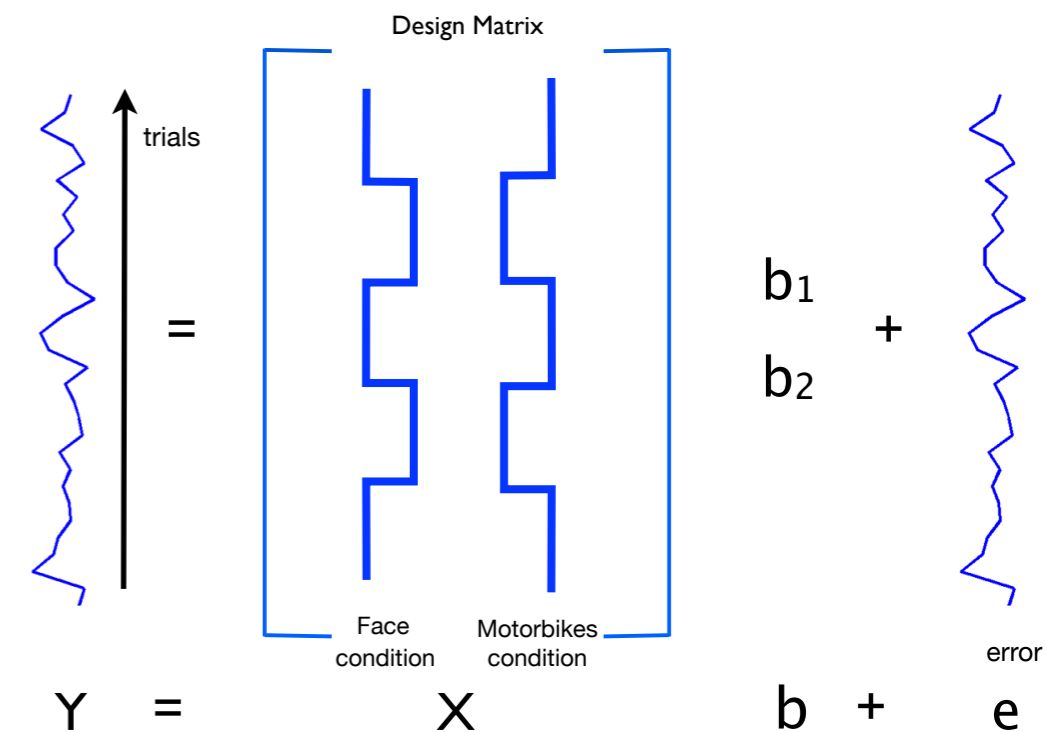
\* as we are doing a one-tailed t-test



# Contrasts

A COntrast of Parameter Estimates (COPE) is a linear combination of parameter estimates, e.g.

$$\text{Contrast } [1 \ -1] \text{ gives a COPE} = 1 \times B_1 - 1 \times B_2 \\ = B_1 - B_2$$



Test the null hypothesis that  $B_1 - B_2 = 0$

**e.g. where in time and space is there more\* activity in response to the faces than the motorbike condition?**

\* as we are doing a one-tailed t-test

# OAT - OSL's Analysis Tool

- **Task-based** analysis in:
  - ➔ sensor space, or
  - ➔ source space (e.g. via beamforming)

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- **Task-based** analysis in:
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- **In:**
  - ➔ time domain (e.g. ERF-style), or
  - ➔ in time-frequency domain (e.g. induced responses)

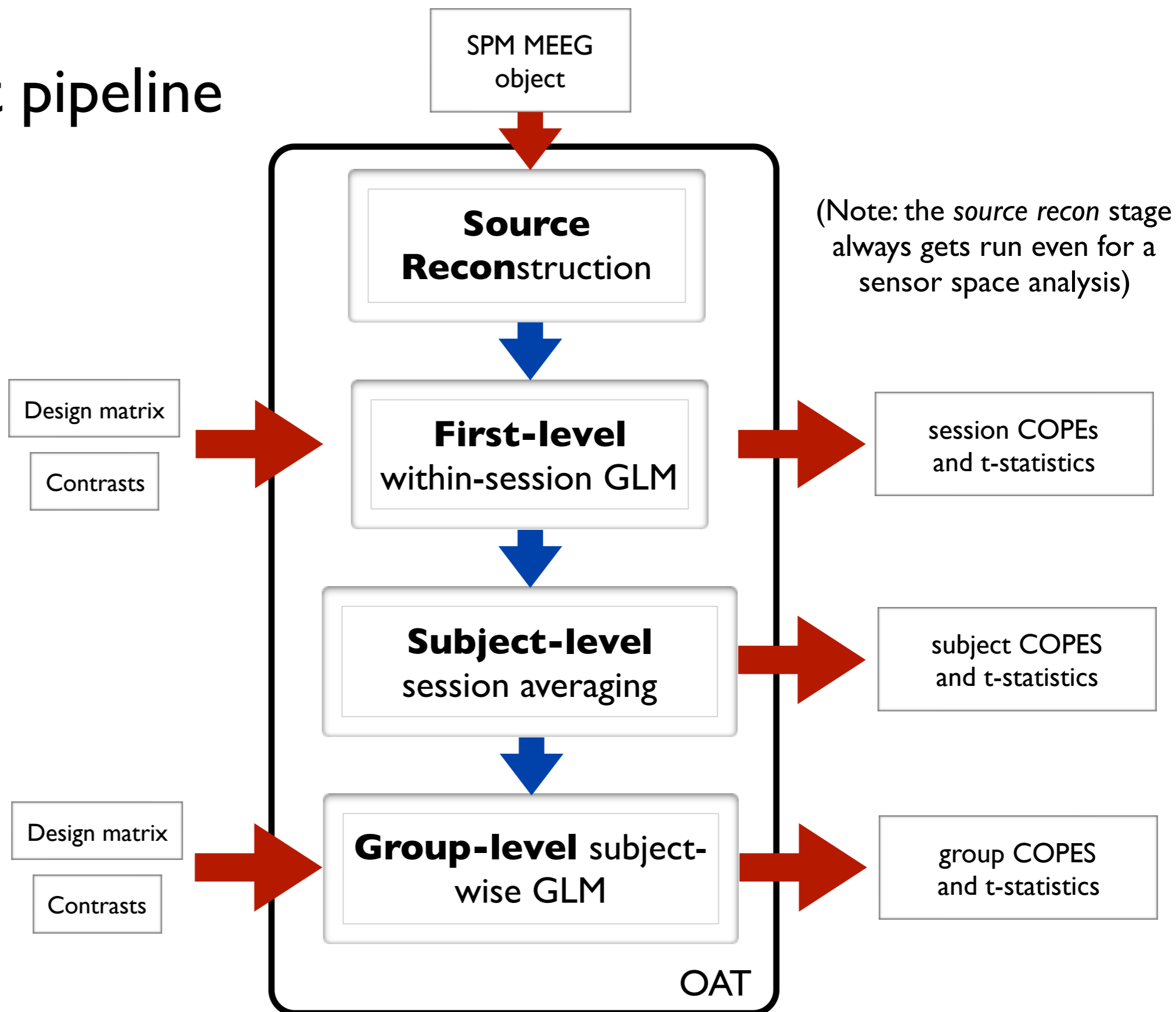


# OAT - OSL's Analysis Tool

- **Task-based** analysis in:
  - ➔ sensor space, or
  - ➔ source space (e.g. via beamforming)
- **In:**
  - ➔ time domain (e.g. ERF-style), or
  - ➔ in time-frequency domain (e.g. induced responses)
- **First-level (within-session) analysis, using:**
  - ➔ trial-wise GLM on epoched data
  - ➔ time-wise GLM on continuous data
- **Group-level (between-subject) subject-wise GLM analysis**

# OAT Pipeline Stages

- 4 distinct pipeline stages:



# OAT Setup

- Set some mandatory fields, and then use `osl_check_oat` call to setup an OAT struct:

➔ `oat = osl_check_oat(oat);`

# OAT Setup

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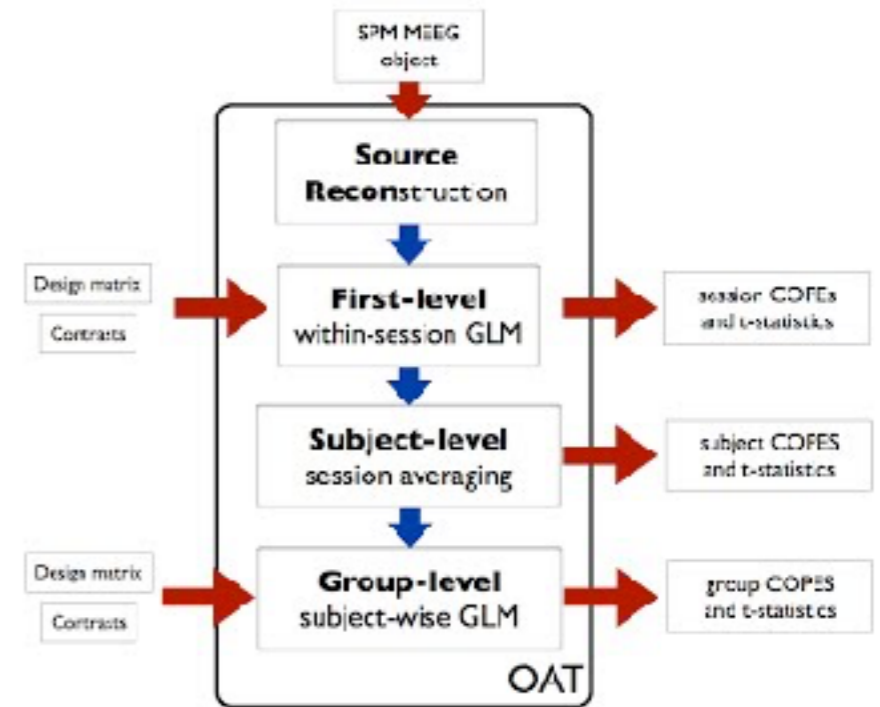
- Settings are organised by the 4 distinct stages of the pipeline:

➔ `oat.source_recon`, e.g.

➔ `oat.first_level` (GLM within-session analysis)

➔ `oat.subject_level` (within-subject averaging)

➔ `oat.group_level` (GLM subject-wise analysis)



# OAT Setup

- The *oat* gets stored in the directory specified in *oat.source\_recon.dirname*, with a *.oat* suffix
- A previously setup/run *oat* can be loaded into Matlab with:
  - *oat.source\_recon.dirname='/path/oatname'*;
  - *oat=osl\_load\_oat(oat)*;

# Some `oat.first_level` settings

- Set time range and freq range using:
  - `oat.first_level.time_range = [-1 2] % secs around stimulus onset`
  - `oat.first_level.tf_freq_range = [1 45] % Hz`

# Some `oat.first_level` settings

- Set time range and freq range using:
  - `oat.first_level.time_range = [-1 2] % secs around stimulus onset`
  - `oat.first_level.tf_freq_range = [1 45] % Hz`
- To do an ERF analysis set `oat.first_level.tf_method='none'`
- To do a Time-Frequency (TF) induced response analysis set `oat.first_level.tf_method='hilbert' % or 'morlet'`

# Running OAT

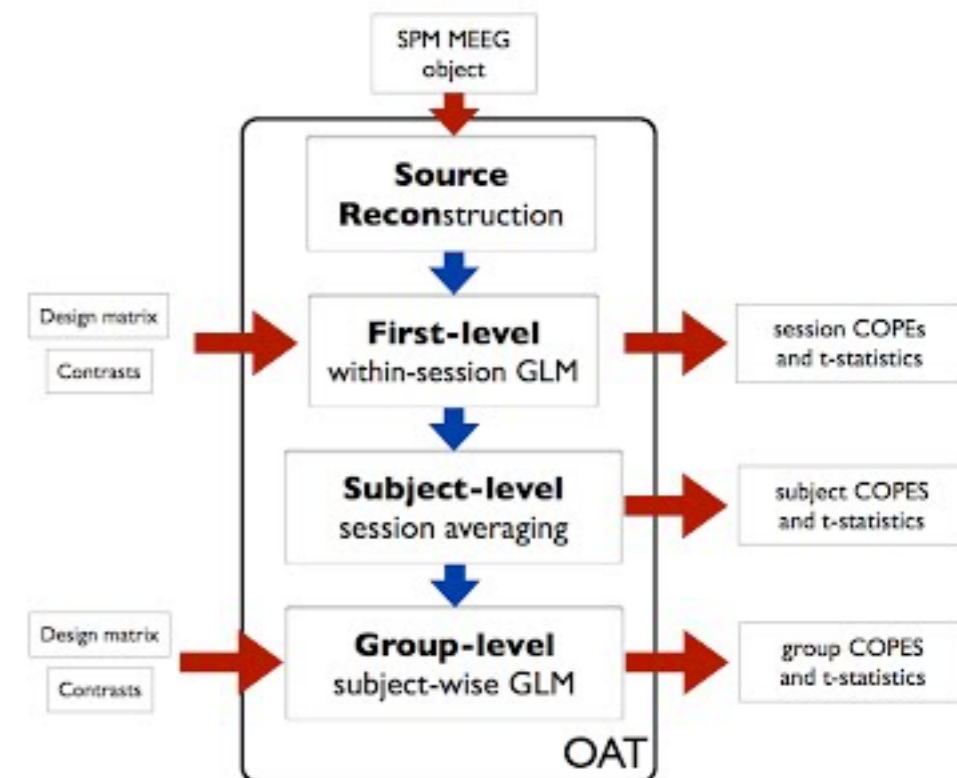
- Use `osl_run_oat` to run an OAT:

➔ `oat=osl_run_oat(oat);`



# Running OAT

- Use `osl_run_oat` to run an OAT:
  - ➔ `oat=osl_run_oat(oat);`
- This only runs the stages specified in `oat.to_do`, e.g.:
  - ➔ `oat.to_do=[1 1 0 0];` only runs `source_recon` and first-level stages



# OAT output

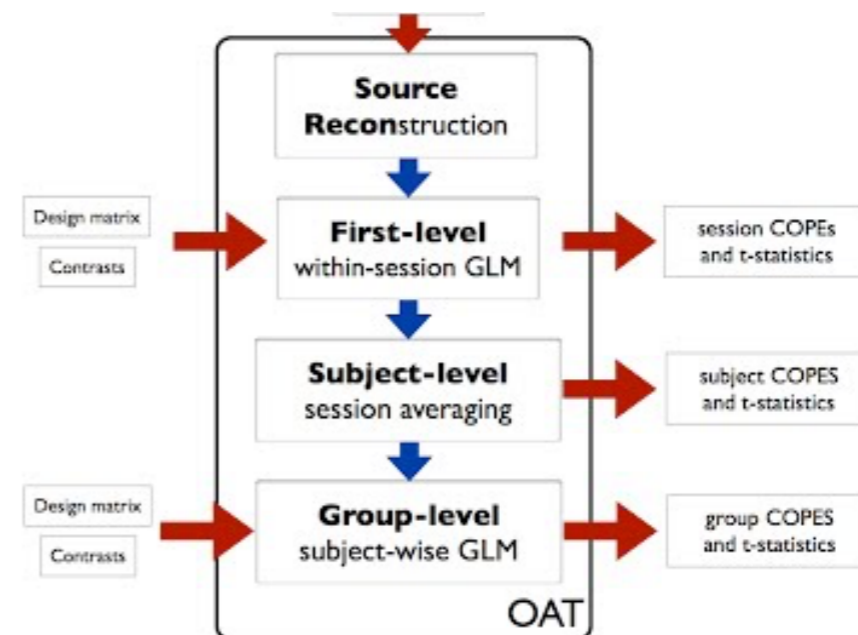
- After running, the *oat* struct contains filenames of the outputs for each stage of the pipeline:

➔ `oat.source_recon.results_fnames`

➔ `oat.first_level.results_fnames`

➔ `oat.subject_level.results_fnames`

➔ `oat.group_level.results_fnames`

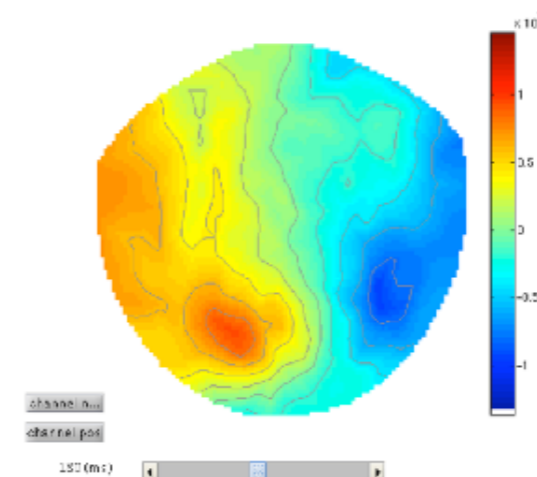


- These can be loaded into Matlab, e.g. to load session 2's first level results use the call:

➔ `res=osl_load_oat_results(oat, oat.first_level.results_fnames{2})`

# Viewing OAT output

- It is highly recommended that you inspect *oat.results.report* (an HTML page), to ensure that OAT has run successfully (See the practical)
- In sensor space, use:
  - Use *osl\_stats\_multiplotER* and *osl\_stats\_multiplotTFR* to call Fieldtrip interactive topoplots
  - The two orientations of the *MEGPLANARs* are combined (in the *first\_level* stage) by rectifying and adding



# Practical

Sensor space trial-wise GLM using OAT on **epoched** task data:

- a) Time-domain (ERF) analysis
- b) Time-frequency (induced response) analysis